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(54) **Apparatus and Method for incrementally advancing a plurality of product carrier plate means**  
Apparat und Verfahren zum schrittweisen Vorschieben einer Mehrzahl von Produktaufnahmeplatten  
Appareil et procédé pour l'avancement incrémentiel d'une pluralité de plaques pour recevoir un produit

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(73) Proprietor: **McNEIL-PPC, INC.**  
**Milltown New Jersey 08850 (US)**

(72) Inventor: **Berta, Norbert I.**  
**Devon, PA 19333 (US)**

(74) Representative:  
**Mercer, Christopher Paul et al**  
**Carpmaels & Ransford**  
**43, Bloomsbury Square**  
**London WC1A 2RA (GB)**

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**EP-A- 0 246 693 EP-A- 0 448 231**  
**US-A- 4 921 108**

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## Description

The present invention relates to apparatus and methods for incrementally advancing a plurality of product carrier plates through a product feed means of a product coating system.

The present invention is related to US-A-4921108; US-A-4867983; US-A-4820524; US-A-4966771; and EP-A-0448231.

The present invention is also related to European patent applications EP-A-0611032, EP-A-0614654, EP-A-0607009 and EP-A-0607008, all filed concurrently herewith.

Many products, from prescription drugs to commonly available vitamin tablets to candy, are manufactured in a form which may be described as a "tablet." The primary function of a tablet is to provide a single dose or "serving" of the product in a manner which is convenient to manufacture, package and consume. As pointed out in my previous patents and applications, referenced above, it has been found that certain individuals suffer from physiological and psychological problems which impede their ability to swallow tablets. It has also been found that by providing tablets with a smooth coating, such as a coating comprised of gelatin or a gelatinous substance that the "swallowability" of a tablet is greatly enhanced. Such coatings and the general considerations involved in their application, such as preparation and drying time, are well known to those of ordinary skill.

In addition to enhanced swallowability, there are numerous other reasons that it is desirable to provide a coating on a tablet. Such coatings protect the underlying product from deterioration and also serve to permit identifying colors or markings to be incorporated onto the design of the product, promoting product differentiation and brand identification. As pointed out in my previous patents and applications, it is also desirable in some instances to overlap two or more coatings to form a seam, thereby simulating the appearance of a hard gelatin capsule while providing a coated, solid (and thus tamper resistant) product.

Methods and apparatus for applying a gelatinous coating or other coating to a product which is in the form of a tablet are well known to those of ordinary skill. Such methods may include pan dipping or vacuum spraying of the coating material on to the tablet. Such methods are crude, however, producing uneven coatings which are generally unacceptable for commercial use. In an effort to improve the state of the art, the inventions disclosed by my previous patents and applications have provided methods and apparatus whereby individual products are held partially within a sleeve or "collet" and the exposed portion of the product precisely lowered into a dipping tank. As disclosed, bars or plates containing a plurality of product to be dipped are conveyed and rotated and the product itself is manipulated to provide even coatings of high quality and consistency at high

volume. These inventions, however, do not permit every type of product such as certain styles of tablets and medicaments to be coated--or at least to be coated in a particular manner. For example, dipping the circular face of a substantially cylindrical tablet whose height is relatively small compared to its diameter would be difficult using the apparatus disclosed by my prior patents and applications, particularly if a circumferential seam is desired. Other examples include the difficulty of coating either a fragile product or applying fragile coating compositions. It has been found that certain coatings will be marred by the friction fit within the collets or similar retaining devices making these unsuitable for use in the apparatus of my prior inventions.

It is known to transport individual tablets or capsules through an immersion coating bath by retaining the tablets on individual vacuum tubes. For example, U.S. Patent 3,896,762--Banker discloses a rotary coating apparatus for pharmaceutical solid dosage forms. Since the surface of the coating is horizontal it is tangential to the path of the tablet; accordingly, Banker discloses that it is necessary to rotate the vacuum tube holding the tablet around its longitudinal axis to achieve an even coating. There are, however, a number of practical shortcomings in the apparatus disclosed. First, although a dryer and ejector are disclosed, the overall system does not lend itself to high volume production or provide for modifications in drying time or inspection, etc. Secondly, the system disclosed by Banker is directed to passing one-half or more of the total depth dimension of the tablet through the coating solution. The tablet is then randomly ejected, with no provision being made to align or otherwise control the orientation of the tablet and the uncoated portion, if any, which exists. Moreover, there is no provision for adjusting the coating to achieve multi-colored or capsule-like coated products. Therefore, one of ordinary skill will appreciate that the system disclosed by Banker is of limited use in current manufacturing environments, where high volume and flexibility are important, along with the need for consistency and high quality.

Therefore, there exists a need for methods and apparatus which can consistently place a precisely defined amount of coating material on an individual product. Such methods and apparatus should be capable of producing coated products at high volume and should possess inherent flexibility to permit new designs and types of coatings to be incorporated without an undue degree of retooling. Moreover, it is extremely important that the products be introduced into the system in a highly controlled manner to enable to coatings to be accurately applied.

EP-A-0485138 describes methods and apparatus for providing a gelatin coating on a plurality of products such as tablets held in a product carrier plate means.

US-A-4921108 describes a feeder device for inserting solid medicaments, such as caplets, into a carrier plate for dipping in gelatin.

EP-A-0194505, on which the preambles of claims 1 and 10 are based, describes a capsule filling apparatus comprising a turntable supported for intermittent rotation about a vertical shaft. Successive capsule mounting, filling and capping operations are accomplished at work stations spaced around the turntable. The capsules are supplied from a delivery drum into receiving holes on the turntable by means of a transfer palate that is driven in a linear, reciprocating motion by means of a cam mechanism.

EP-A-0246693 describes a method of manufacturing pharmaceutical capsules, according to which circulating capsule pins are dipped in a solution of thermogelling material, and are then rotated upside-down to achieve a uniform thickness of solution adhering to the pins. After thermal treatment to gel the solution, the formed gel is dried and removed from the capsule pins.

EP-A-0448231 describes gelatin coated caplet medicaments formed by retaining a plurality of caplets in holes in a plate carrier, incrementally advancing the plates to a first dipping means and coating a first end of the caplets with a first coating material, drying the coating, displacing the caplets through the holes in the plate carrier to expose an uncoated end of the caplets, dipping this end in gelatin of a second colour, drying, and removing the coated caplets from the plate carriers.

EP-A-0118856 describes a supply hopper assembly for use in a tablet transporting apparatus. The assembly comprises a rotary drum having recessed pockets therein connected to a vacuum means for retaining the tablets therein by suction. The hopper assembly further comprises a container having a bottom plate inclined downwardly towards the periphery of the drum and terminating at a particular position in a nozzle assembly for supplying jets of compressed air into the container to facilitate the supply of the tablets into the recessed pockets.

The present invention provides apparatus for incrementally advancing a plurality of carrier plate means through a feeder means of a product processing system, as defined in claim 1. The present invention further provides a method for incrementally advancing a plurality of product carrier plate means through a feeder means of a product processing system, as defined in claim 10.

In one embodiment a box cam mechanism moves a first plate engagement bar in four directions to advance the carrier plates and a two-way cam mechanism moves a second plate engagement bar in two directions to alternately lock and unlock the plates. The plate indexing means is connected to the feeder device in order to coordinate the loading of tablets onto holders in the carrier plates in cooperation with the advancement of the plates. A setting pin is connected to the plate indexing means to properly seat the loaded tablets in their individual holders prior to advancing to other processing stations. In one embodiment, a passive loading mechanism is described in which tablets are

loaded onto the holders by movement of the carrier plates. In another embodiment, the tablets are loaded using a rotatable vacuum pick-up head system for picking up tablets from the feeder device and placing them onto the product holders. The feeder device is also provided with selection means for sifting out partial tablet pieces. The precise indexing of the product carrier plates and the loading and setting of the tablets onto the plates in accordance with the present invention greatly increases the efficiency of the gelatin coating processing system resulting in greater productivity and lower costs.

In the accompanying drawings:-

FIG. 1 is a partially diagrammatic, partially schematic representation of a coating apparatus comprising the present invention.

FIG. 2 is a broken away, partially cross-sectioned side view of a portion of the apparatus of FIG. 1.

FIG. 3 depicts a cross-sectional view of the tablet holders and plate used in one embodiment of the present invention.

FIG. 4 is a broken away cross-sectional view of the plate of FIG. 3, illustrating the tablet holder and vacuum tube used in one embodiment of the present invention.

FIG. 5 is a partially diagrammatic, partially schematic representation of the steps of a preferred method for coating a tablet comprising a method according to the present invention.

FIG. 6 is a broken away cross-sectional view of a portion of another coating apparatus comprising the present invention in which a band of coating material is applied to the products.

FIGS. 7a and 7b are cross-sectional views of another embodiment of a tablet holder for use in the present invention.

FIG. 8 is a plan view of a product carrier plate for use in one embodiment of the present invention.

FIG. 9 is a partial elevational view of the plate indexing means of the present invention.

FIG. 9a is a cross-sectional view taken along lines 9-9 of FIG. 9.

FIG. 10 is a cross-sectional view taken along lines 10-10 of FIG. 9.

FIGS. 11a-11e are a schematic representation of the sequential movement of the engagement bars

of the indexing means of FIG. 9.

FIG. 12 is a diagrammatic representation of the feeder means for use in the present invention.

FIG. 13 is a diagrammatic representation of a perforated plate of a separation means of one embodiment of the feeder means for use in present invention.

FIGS. 14a and 14b are cross-sectional views of the passive means for dispensing tablets onto a product holder.

FIG. 15 is a cross-sectional view of the setting means of the present invention.

FIG. 16 is a cross-sectional view of one embodiment of a vacuum pick-up device of the product dispensing means of the present invention.

FIG. 17 is a cross-sectional view of another embodiment of the dispensing means of FIG. 16 with a setting means attached thereto.

A generalized representation of the apparatus comprising a preferred embodiment of the present invention is shown in FIG. 1. It will be understood that the descriptions set forth may be applied to numerous types and shapes of products. The type of tablet illustrated and the sequence shown are for purposes of explanation only.

A plurality of the product 10 to be coated is placed in a feeder means 80. Preferably, the feeder will be comprised of a hopper 82 and a series of feeder tubes 84 which align, orient and dispense the product 10 in the appropriate manner. Initially disposed directly beneath the feeder tubes 84 and in registration therewith is a plate 50. The plate 50 has a plurality of tablet holders 30 which, as explained below, restrain the product during certain portions of the coating process. The tablet holders 30 preferably correspond to the feeder tubes 84 and thus, most preferably, each tube 84 feeds a single product 10 into a single tablet holder 30.

Conveyor means transfer the plate 50 from the feeder 80 to the vacuum chamber 60. In a preferred embodiment shown in FIG. 1, the vacuum chamber 60 is adapted to receive and make vacuum tight connections with two plates 50. As shown by the arrows, the vacuum chamber 60 is further provided with manipulating means whereby it may be moved up and down, and rotated about a pivot point 62.

A first dipping tank 120 is disposed beneath the vacuum chamber 60 and is filled with a quantity of coating material. Preferably a coating material such as gelatin is used and, most preferably, the dipping tank 120 is provided with pumps and conduits whereby the coating material is continuously circulated. As illustrated, the dipping tank is most preferably constructed to form a

meniscus surface 122 by pumping the coating material into an inner tank 124 which is permitted to overflow into the larger tank 120. Such a system prevents the coating material from hardening while the apparatus is in use and helps to ensure that the coating material presents the same even and substantially level surface to the product being dipped at all times.

In operation, the plate 50 is moved into engagement with the vacuum chamber 60 and then the chamber 60 and the plate 50 are rotated one-half revolution. As explained below, the vacuum chamber 60 creates a vacuum within the tablet holders 30 which holds the product 10 in place and in the correct orientation to be dipped. The vacuum chamber 60 is next lowered into dip tank 120 to a predetermined depth and then withdrawn. The vacuum chamber 60 is then rotated one and one-half revolutions in order to return the plate 50 to its original orientation. The additional full revolution beyond that required provides a dwell time, permitting the coating to initially "set" and also prevents the coating from running or sagging due to gravity by constantly reorienting the product 10. However, a rotation of as little as one-half of a revolution may be adequate in some instances. At this point, the plate 50 may be returned to the conveyor means and removed from the vacuum chamber 60.

The design of the vacuum chamber 60 and placement of the dip tank 120 illustrated permit a wide variety of coatings to be effectively and efficiently achieved. Although the dipping of a substantially cylindrical tablet having concave faces to form a coating having circumferential seam is illustrated, those of ordinary skill will understand that numerous other shapes of product, as well as other coating schemes are possible using the apparatus disclosed. As will be explained below, the shape of the tablet holders 30 and the design of the sub-components of the vacuum chamber 60 may be readily adapted for particular requirements. Also, as illustrated in FIG. 1, throughput may be increased by designing the vacuum chamber 60 to form a vacuum tight seal with further plates 50, such that each time the vacuum chamber 60 is rotated, a plate 50 which has already been lowered into the dipping tank 120 is returned to the conveyor means.

After the plate 50 containing the partially coated product 10 is removed from the vacuum chamber 60 the plate may be passed through a dryer means 130 for curing the coating material. As will be understood by those of ordinary skill, the dryer 130 will be chosen to correspond to the heat and moisture requirements of the coating material being used. Radiant heat, forced hot air, microwave dryers and combinations of these types are among the types available. Depending upon the type of dryer 130 chosen, one or more conveyors and other apparatus may be required to transfer the plates 50 into and out of the dryer 130.

After the coating has been cured, the plate 50 is again returned to conveyor means and is preferably

transferred to another location. At this point, although only a portion of each individual product 10 has been coated, it may be desirable to eject the product 10 and consider the process complete. This may be true, for example, where the product has already been coated and the above-described process is carried out to add a second color to a portion of the product.

In a preferred embodiment, however, the present invention forms part of methods and apparatus which permit the uncoated portion of the product 10 to be coated. First, a second plate 50' is positioned in registration with the product contained on the first plate 50, as illustrated in FIG. 1. The second plate 50' is lowered until the coated side of the product 10 is disposed within the tablet holders 30' of the second plate 50'. The resulting "sandwich" of the first plate 50, the product 10 and the second plate 50' is then rotated one-half revolution by the conveyor/manipulator means. As shown, the positions of the plates 50,50' are thus reversed, and when the first plate 50 is removed the uncoated portion of the product 10 is exposed. The second plate 50' may then be transferred to the starting point of the dipping process and put through the sequence of manipulations necessary to form a coating which were set forth above using either the same apparatus or further apparatus, using either the same coating material or a different coating material.

In the instance where the same apparatus is used to place coating upon the uncoated portion of the product 10, the second plate 50' may be preferably conveyed or otherwise transported to a location just before the vacuum chamber 60, i.e., between the vacuum chamber 60 and the feeder 80 illustrated in FIG. 1. The second plate 50' would simply be inserted into engagement with the vacuum chamber 60 and the above described apparatus would carry out substantially the same sequence of functions in terms of dipping the product 10, curing the coating as needed, etc. After the product 10 has been fully coated and cured, it may be ejected prior to the transfer stage between the first and second plates 50,50'.

In another embodiment of the apparatus and method comprising the present invention, after the partially coated product has been transferred to the second plate 50', the plate 50' may enter a duplicate series of apparatus, such as that described above with reference to FIG. 1. In other words, a second vacuum chamber, dipping tank, dryer, and manipulating and conveying apparatus may be provided. After the product 10 is coated and cured using this second set of apparatus, the completed product is ejected.

Referring now to FIG. 2, a more detailed view of the vacuum chamber 60 described above is shown. As explained above, in a preferred embodiment two plates 50 (or 50') are retained in a vacuum tight seal upon the vacuum chamber 60, thereby permitting more efficient indexing between the raising and lowering of the apparatus and the infeed and outfeed of the plates 50 from

the vacuum chamber 60.

As shown, the entire chamber may be raised or lowered to bring the product 10 into contact with the surface of the coating material 122. The vertical motion also preferably provides a transfer between the vacuum chamber 60 and the conveyor means, as shown in phantom in Fig. 2. This latter vertical movement also provides clearance when the vacuum chamber 60 is rotated during the dipping process explained above with reference to FIG. 1.

Further details of the vacuum chamber 60 are shown in FIG. 3, which illustrates broken-away section of the plate 50 and the vacuum chamber 60. As seen in cross-section, the plate 50 has a plurality of tablet holders 30 inserted into a series of openings. The plate 50 rests upon the vacuum chamber 60 and forms a seal therewith. A plurality of vacuum tubes 100 extend through the tablet holders 30 and, when in use, engage and slightly lift the product 10 from the tablet holders 30 as shown. The vacuum created within the vacuum chamber 60 is channeled through the vacuum tubes 100 by a manifold or similar means, thereby permitting the vacuum to act upon the surface of the product 10 when contacted by the vacuum tubes 100. By providing vacuum tube actuator means 102 for raising and lowering the vacuum tubes 100 relative to the vacuum chamber 60, the vacuum tubes may be selectively placed in the raised position illustrated. The actuator 102 may be a common bar or mounting structure which is moved by a gear, cam or pulley system.

When in the position illustrated, it is possible to invert or otherwise manipulate the product 10 as described above without friction or the use of mechanically actuated clamps. The vacuum handling system disclosed by the present invention provides a secure retention of the product while minimizing the possibility of damaging either the coating or the product 10 itself. As explained above, the methods and apparatus of the present invention are useful for numerous shapes and sizes of product 10, however, most preferably, the product 10 will have one or more curved surfaces, as illustrated. The curved surfaces permit the tubes 100 to be made from a rigid material such as stainless steel. Those of ordinary skill will realize however, that nearly any shape and any orientation of product may be retained using appropriately designed vacuum tubes. Finally, in certain instances it will be desirable to provide a cushion or resilient tip on the distal end of the vacuum tube in order to ensure a sufficient grip.

Referring now to FIG. 4, one embodiment of the tablet holder 30 is illustrated. A shoulder 32 is formed at a first end of the tablet holder to provide a positive stop. A groove is formed at a second end, into which an "O" ring or the like may be engaged to retain the tablet holder 30 in the plate 50. As will be understood by those of ordinary skill, the tablet holder 30 and the plate 50 may be in certain instances formed as an integral component. FIG. 4 also illustrates the vacuum tube 100 in

the withdrawn position. When the vacuum tube 100 is in the withdrawn position, the depression formed in the tablet holder 30 is the only means for restraining the product 10 (not shown in FIG. 4).

FIGS. 7a and 7b show a second embodiment of the tablet holder for use in plates 50. Tablet holder 31 shown in FIGS. 7a and 7b is provided with a plurality of slots 33 forming resilient fingers 35. FIG. 7a is a cross-section taken through the slots 33, and FIG. 7b is a cross-section taken with the holder 31 rotated 90° from its position in FIG. 7a. In the embodiment shown in FIGS. 7a and 7b, a pair of slots 33 are provided thereby forming a pair of resilient fingers 35. Slots 33 are disposed longitudinally through the walls of holder 31. Holder 31 is generally in the form of a cylinder having a central bore 37. Tablet holder 31 is retained in the opening 39 of plate 50 by shoulder portion 41 on one end and angled flange 43 on a second end. For ease in installation the size of upper surface 45 of angled flange 43 may be significantly reduced at the portion of the side walls located immediately adjacent to slots 33 as shown in FIG. 7a. The flange 43 may gradually increase to its largest surface area located 90° from slots 33 as shown in FIG. 7b. The holder 31 is also provided with seat 47 for accepting a tablet therein. It will be understood by those of ordinary skill that the seat 45 may be shaped appropriately to match the shape of the product being held.

The holder 31 is a "push-in" holder that does not require o-rings or the like that are susceptible to wear and tear. In order for the holder 31 to be secured in the plate 50, the outer diameter of the annular resilient fingers 35 forming the cylinder of holder 31 must be slightly larger than the diameter of the opening 39 in plate 50. The angle of flange 43 enables the holder 31 to be inserted through the opening 39 and to cause the fingers 35 to be slightly compressed toward each other as the holder is passed through the plate 50. When the flange 43 clears the opening 39 and plate 50, the resilient fingers 35 spring back to their original position causing flange 43 to engage plate 50 thereby securing the holder 31 therein.

FIG. 8 shows a plan view of a carrier plate 50 for retaining the plurality of product holders 30 or 31. The carrier plate 50 of FIG. 8 includes a plurality of longitudinal rows of individual product holders 31. The plates 50 are preferably from 102 to 127 mm (4 to 5 inches) wide and approximately 13 to 25 mm (one-half to one inch) thick. In one embodiment, the plate 50 is made about 584 to 610 mm (23 to 24 inches) in length enabling the plate to include 7 rows each containing 33 holders for a total of 231 holders.

A preferred embodiment of the carrier plate 50 of the present invention is machined from tool plate aluminum. It is also preferred that the aluminum have a protective coating such as an anodized coating applied to the surface. The plate 50 is rectangular and symmetrical, having four easily spaced slots 51 disposed near

the four corners which engage the conveyor and/or holding means. Also provided at either end are alignment and transport holes 52 which contain retaining bushings 53 which are used to manipulate the plate 50 as it is advanced through the feeder means 80 and through other processing stations.

A preferred embodiment of the methods comprising a method of the present invention is illustrated by the sequence of views in FIG. 5. For purposes of illustration and explanation a single product 10, vacuum tube 100 and tablet holder 30 are illustrated, along with broken away portions of other apparatus such as the plate 50. As shown in the upper left section of FIG. 1, a plate 50 containing a tablet holder 30 is positioned beneath the feeder means 80 for feeding a tablet described above and a product 10 is disposed within the tablet holder 30. Next, the plate 50 containing the individual products 10 is moved into the vicinity of the vacuum chamber 60, where it is cleaned of dust and particulate matter. For clarity, the representation of the vacuum chamber 60 is omitted from the other views shown in FIG. 5. An individual vacuum tube 100 is then brought into position and placed in close proximity or contact with the product 10. At this point, the vacuum created within the vacuum tube 100 "picks up" or engages the product 10. After the individual products 10 have been engaged by the vacuum tubes 100, the entire plate 50 is rotated one-half of a revolution, suspending the product 10 by the vacuum tube 100. The vacuum tube 100 and the product 10 attached thereto may now be moved into position and lowered into a coating tank 120. The depth to which the product 10 is lowered is a function of the motion of the vacuum tubes 100 and plate 50, which may be precisely regulated by hydraulic actuators, gear trains or other means for actuating the vacuum tube 100 and/or moving the plate 50. The vacuum tube 100 and the partially coated product 10 are then withdrawn from the coating tank 120, but the product 10 is not fully withdrawn into its holder 30. Instead, the plate 50 and partially extended vacuum tubes 100 are rotated one and one-half revolutions, returning the plate 50 to its initial orientation. The additional revolution provides a dwell, permitting the coating to initially set, as well as aiding in the provided evenness of the coating by preventing the coating from running due to gravity. In certain embodiments, however, this dwell may be unnecessary and the plate need only be rotated one-half of a revolution. After the plate 50 has been returned to its initial position, the vacuum tube 100 may be withdrawn until the product 10 again rests in a holder 30 within the plate 50. Once the vacuum tube 100 has been sufficiently withdrawn, the vacuum connection to the product 10 is broken and gravity and the holder 30 restrain the product 10.

As shown at the lower left portion of FIG. 5, once the individual products 10 have been released from the effect of the vacuum, the plate 50 bearing the partially coated individual products 10 may be moved into a dryer 130. Using conveyors or other conventional

means, the plates are pushed into the dryer 130 and dried. After the coating has cured and the plates 50 have exited the dryer 130, a second plate 50' is moved into position such that the tablet holders 30' in the second plate 50' are in registry with the tablet holders 30 in the first plate 50, which contain the partially coated product 10. The second plate 50' is lowered toward the first plate 50 until the tablet holders 30' in the second plate 50' have engaged the product held in the first plate 50. Thus, as illustrated, the product 10 is "sandwiched" between the first and second plates 50,50'. The pair of plates 50,50' are then rotated one-half revolution, thereby reversing the relative positions of the first and second plates 50,50'. The first plate 50 is then raised, leaving the uncoated portion of the product 10 on the top, exposed, and the coated side on the bottom, i.e., within the tablet holder 30 of the plate 50'.

At this point, the method illustrated has completely coated and cured a coating on about one-half of the product 10. It will be understood, however, that the above-described method may be repeated by transferring the plate 50' shown in the lower right section of the illustration to the upper left section, in other words, to the beginning of the process at the point immediately after the individual products 10 have been loaded into the plates 50. In this embodiment, the above-described process is repeated and the remainder of the product 10 is coated. It should be further understood, however, that in any event, more or less than one-half of the tablet may be coated to provide different overall coating effects. For instance, if both "passes" coated less than one-half the height of the tablet, a band of uncoated product would remain exposed. On the other hand, if one or both of the "passes" were carried out to a depth substantially greater than one-half the height of the tablet, an overlapped "seam" appearance would be created.

Referring now to FIG. 6, another feature of certain embodiments of the coating apparatus for use with the present invention is illustrated. In these embodiments, the vacuum tube 100 will be constructed such that it may be rotated about its longitudinal axis as shown by arrow a in FIG. 6. As understood by those of ordinary skill, such rotation may be accomplished using gear trains, belts and pulleys or other means for transferring rotational motion to a shaft. While rotating, the vacuum tube 100 is also acted upon by a source of vacuum, either the vacuum chamber 60 discussed above, or another source. The product 10 is thus firmly held in place upon the rotating vacuum tube 100 as shown. While the product 10 is rotating, it is brought into contact with a rotating wheel 210 or other application means for applying a coating. Preferably, the rotating wheel 210 provided is shaped and manipulated so as to come into close proximity with a portion of the product 10, such as the central "edge" shown. As the wheel 210 and product 10 rotate, the wheel 210 also passes through a quantity of coating material 222 and precisely coats a portion of

the product 10. The wheel 210 rotates about a shaft 202 in the direction shown by arrow b and is mounted on a support structure 200 at an appropriate angle.

In this way, a relatively narrow stripe or band of coating material may be applied to a product. Most preferably, the product and the means for applying the coating rotate and are placed in close proximity. The means for applying the coating is preferably at least partially immersed in a quantity of coating material and passes therethrough while rotating. Using the embodiments illustrated in FIG. 6, it is possible not only to provide a different color "band" or stripe, but to also increase the thickness of the coating in a specified section, thereby creating the appearance of a seam or an overlapped gelatin capsule.

Referring now to FIG. 9, a novel plate indexing means 300 for incrementally advancing a plurality of product carrier plates 50 through feeder means 80 of the present invention can be described. The plate indexing means 300 includes a first engagement means 302 for engaging one or more of the product carrier plates 50 and a first cam means 304 for providing motion in at least two directions to the first engagement means 302. In one direction of movement the first cam means moves the first engagement means 302 from a first position to a second position which thereby advances the product carrier plate 50 an incremental predetermined distance. In the second direction of movement, the first cam means 304 returns the first engagement means 302 to the first position. The first engagement means 302 engages the product carrier plate 50 while moving from the first position to the second position. The plate indexing-means 300 incrementally advances the product carrier plates 50 through the feeder means, partially shown at 80, where tablets 10 are dispensed onto the individual holders in the plates 50. In a preferred embodiment of the first cam means, motion in four orthogonal directions to the first engagement means is provided. In this preferred embodiment, the first engagement means is moved into third and fourth positions, out of engagement with the carrier plates 50, for returning the first engagement means from the second position to the first position.

In a preferred embodiment of the plate indexing means 300, a second engagement means 306 is provided for engaging one or more of the plate means 50. The second engagement means 306 is moved between a first position engaging the plate means 50 and a second position out of engagement with the plate means 50. The second engagement means 306 engages the plate means 50 to prevent advancement of the plates 50 during the time when the first engagement means is being returned from its first position to its second position. During this time, the carrier plates 50 must be maintained in position so that the first engagement means will be able to re-engage the plates when it is returned to the first position. Any movement of the plates during the return may result in the plates being

unable to be re-engaged causing a shut down of the system. The second engagement means 306 is moved into its second position out of contact with the plates to allow for the controlled advancement of the plates by the first engagement means 302.

Engagement means 302 is comprised of an engagement bar 310 that extends longitudinally over the width of a plurality of plates 50. In the illustrative embodiment shown in FIG. 9, the engagement bar 310 extends over a part or all of six plates. Secured to a bottom surface of engagement bar 310 are a plurality of engagement pins 312. The pins 312 are adapted to fit snugly into retaining bushings 53 of carrier plates 50. Mounted onto an upper surface of engagement bar 310 is cam means 304. As shown in FIG. 9, cam means 304 is a box cam comprised of a cam follower 314 and a pair of cams 316 positioned in a pair of cam openings 318. As will be more fully explained below, the preferred embodiment of cam means 304 shown in FIG. 9 provides movement to engagement bar 302 in four orthogonal directions in the same plane thereby creating a "box" motion. This "box" motion causes, for every 360° of motion of cams 316, engagement pins 312 to incrementally move from a first position, through second, third and fourth positions, and back to the first position. The "box" motion is provided by the shape of the cams 316 and openings 318. As can be seen in FIG. 9, openings 318 are generally in the shape of a square. Each 90° of motion of cam 316 will cause the cam follower and hence the engagement bar to move in one of the four orthogonal directions. A full 360° of motion therefore provides movement in all four orthogonal directions.

Engagement means 306 is similar to engagement means 302 and therefore comprises an engagement bar 320 having engagement pins 322 secured to a bottom surface thereof. Cam means 308 is mounted to engagement bar 320 and is comprised of a cam follower 324 having a pair of cams 326 positioned in a pair of cam openings 328. In the preferred embodiment shown in FIG. 9, the cams 326 and openings 328 are designed to provide only two directions of motion in the same plane to engagement bar 320. The openings 328 are rectangular in shape as opposed to the square shape of the cam openings 318. In the illustrative embodiment of FIG. 9, the vertical dimension of openings 318 and 328 are identical while the horizontal dimensions of 328 are longer than the horizontal dimensions of openings 318. The size and shape of cams 316 and 326 are identical. However, 180° of motion of cams 326 is required to effect movement to engagement bar 320. For each 180° of motion of cams 326 only one of two directions of motion along the vertical plane will be provided to engagement bar 320. Engagement bar 320 will hence be moved from the position shown in FIG. 9 where the pins 322 are out of engagement with plates 50 and to a second position in which the pins 322 are in engagement with plates 50. While in engagement with plates

50, engagement bar 320 prevents movement of the carrier plates 50 and thereby acts as a locking mechanism. Cam follower 324 also includes opening 330 for receiving a positioning bar 331 shown in FIG. 9a that, together with locking wheels 333, prevents movement of engagement bar 320 in the horizontal direction. The wheels 333 are mounted to shafts 337 and rotate with the shafts 337 and move up and down with cam follower 324. As indicated above, the apparatus of the present invention is intended to facilitate coating large numbers of tablets. In the embodiment described above, plates 50 are comprised of seven rows of 33 tablet holders. Thus, the feeder means must be able to dispense a single row of 33 tablets simultaneously onto the carrier plates. It is necessary, therefore, that the plate indexing means ensure that each row of 33 tablet holders is advanced to be in proper registration with the feeder tubes so that all the tablets in the row will be properly seated in the holders. In a preferred embodiment of the present invention, a pair of plate indexing means 300 is provided one on each side of plate 50. As shown in FIG. 8, plates 50 include a row of engagement bushings 53 on each transverse side in order to accommodate engagement pins on each side. A single pair of drive shafts that extends through the cams 316 and 318 of both plate indexing means 300 will provide identical movement to both sides of plates 50. This will ensure that the entire row of holders is accurately advanced to be in registration with the entire row of feeder tubes.

The plate indexing means 300 shown in FIG. 9 acts to incrementally advance the carrier plates in a precisely controlled manner. One important feature is that the apparatus of the invention always maintains the carrier plates under a positive control. This is accomplished through the coordinated movement of the pins 312 and 322 in and out of engagement with the transverse rows of engagement bushings 53 in plates 50. As shown in FIG. 8, there is a single row of engagement bushings 53 on each end. The pins 312 and 322 must therefore engage a single row of bushings 53. In order for this to be accomplished, the engagement bars 310 and 320 must have complementary shapes and cooperate in such a manner in order to enable both sets of pins 312, 322 to be positioned along a single longitudinal axis. Referring now to FIG. 10, a plan view of engagement bars 310 and 320 is shown. As can be seen, the bars 310 and 320 have a tongue and groove like fitting arrangement which allows for each of the sets of pins 312 and 322 to lie along a single longitudinal axis. In addition, the width of the "tongues" 332 is less than the width of the "grooves" 334 of engagement bars 310 and 320 which allows for longitudinal movement of engagement bar 310 with respect to engagement bar 320. For the sake of simplicity, the relative longitudinal movement of engagement bar 310 with respect to engagement bar 320 is shown in phantom only at the pin 312 located on the extreme left hand side of the FIG. 10. Position 1, shown in phantom, is the location of the pins 312 prior



to plate advancement. Position 2 is the location of the pins 312 subsequent after plate advancement. Engagement bar 320 does not move in the horizontal plane and therefore pins 322 remain in the positions shown. For a full description of the relative movement of pins 312 and 322, reference to FIG. 11 will be made.

Referring now to FIGS. 11 (a)-(e) there is illustrated the sequential operation of the plate indexing means 300 for incrementally advancing the plates 50. FIG. 11(a) shows an engagement pin 312 in position 1 in which the pin is engaged in a plate 50, while at the same time engagement pin 322 is in position 1' out of engagement with a plate 50. Rotation of cams 316 and 326 90° advances the plates 50 the predetermined distance equal to the center-line to center-line distance between each of the transverse rows of product holders in plates 50. As shown in FIG. 11(b), pin 312 is advanced in the direction of product flow to position 2 causing each plates 50 to be advanced the predetermined distance. As shown in FIG. 11(b), pin 322 remains in position 1', out of engagement with plates 50. As explained above, the first 90° movement of cam 326 does not result in cam 326 contacting cam follower 324 so that no movement will occur to engagement bar 320. As shown in FIG 11(c), upon a second 90° rotation of cams 316 and 326, pin 312 is moved out of engagement with plates 50 to position 3. The second 90° movement of cam 326 causes movement of engagement bar 320 which moves pin 322 downward to position 2' engaging plates 50. Next, as shown in FIG. 11(d) the third 90° rotation of cams 316 and 326 results in pins 312 moving in the opposite direction of product flow to position 4. During this 90° rotation of cam 326, no movement is effected to engagement bar 320 and thus pins 322 remain in position 2' engaged with plates 50. As noted previously, a positioning bar is in contact with cam follower 324 and is connected to the frame assembly of the processing apparatus to prevent longitudinal movement of the engagement bar 320. Thus, by maintaining pins 322 in engagement with plates 50 during the time when pins 312 are out of engagement with plates 50, assures that the plates 50 are always under positive control. As shown in FIG. 11(e), the fourth 90° rotation of cams 316 and 326 results in pin 312 moving downward to position 1 re-engaging plate 50. The fourth 90° rotation of cam 326 results in movement of engagement bar 320 upward moving pins 322 back up to position 1' out of engagement with plates 50.

As noted above, the relative shape of cams 316, 326 and cam opening 318, 328 provide the complementary movement of engagement bars 310 and 320. Referring back to FIG. 9, the first box cam 304 includes an eccentric cam 316 rotatable 360° in the cam follower housing 314, each 90° of rotation, providing a predetermined motion time period and a predetermined dwell time period for the engagement bar 310. In the illustrative embodiment shown in FIG. 9, each 90° of rotation of cam 316 provides a motion period for approximately 72°

of that rotation and a dwell time for approximately 18° of that rotation to move engagement bar 310 in each of the four directions. Likewise, cam 326 is an eccentric cam rotatable 360° that provides for each 180° of rotation a predetermined motion time period and a predetermined dwell time period for the engagement bar 320. In the illustrative embodiment shown in FIG. 9, each 180° of rotation of cam 326 provides a motion time period for about 72° of that rotation and a dwell time period for about 108° of that rotation to move engagement bar 320 in each of two directions.

Plate indexing means 300 as described above, provides precise incremental advancement of the plates 50 through the feeder means to provide accurate feeding and loading of tablets onto the carrier plates. High precision in the loading of the tablets onto the plates is necessary to allow the system to accurately coat the product with the various coating arrangements as desired. Conventional drive components including motors, drive shafts and the like are required to provide the rotation to cams 316 and 326, all of which are well known to those skilled in the art and hence there is no need to provide details of these elements.

Referring now to FIGS. 1 and 12, the feeder means 80 includes hopper 82 and a plurality of feeder tubes 84. Feeder means 80 also preferably includes separation means 86 for eliminating broken tablets so that only full sized tablets are introduced into the hopper 82. Feeder means 80 further includes dispensing means 88 for orienting and depositing one or more products onto the product carrier plates 50. The separation means 86 includes a perforated plate 81, shown in FIG. 13, that is caused to vibrate by a vibrator means 83. A plastic tote or other container 85 containing a supply of product to be coated is attached to a chute 87. As shown in FIG. 12, tablets 10 in tote 85 are allowed to feed into the chute 87 causing the product to travel into a angled chute 89. The tablets 10 are transferred through chute 89 in essentially a single layer to perforated plate 81. The perforated plate 81 and chute 89 are attached to the vibrator 83 and are positioned at an angle whereby vibrations cause the tablets to "walk" across the perforated plate and fall into chute 91. Perforated plate 81 is comprised of a series of holes 93 which are sized just slightly smaller than the diameter of the tablets to be coated. As the product walks across the perforated plate, partial or broken tablets will fall through the holes 93 while full sized tablets will pass completely across the plate and fall into chute 91. A bin 95 is positioned below the perforated plate 81 to collect the broken pieces.

Chute 91 transfers the full tablets 10 to hopper 82 of feeder means 80. Reciprocating drive means 90 causes hopper 82 to move in an up and down motion resulting in tablets 10 entering feeder tubes 84. The dispensing means 88 orients and dispenses the tablets 10 onto the plate means 50. The dispensing means 88 fills a plate 50 one row at a time. In a preferred embodiment of the

present invention, feeder tubes 84 contain a linearly disposed plurality of product 10 to be deposited. It will be understood that FIG. 12 is a side view, partially cross-sectioned, therefore only one "column" of product is visible. However, in a preferred embodiment, a column of product 10 is positioned over each product holder across an empty row of plate 50. In the preferred embodiment shown in FIGS. 9 and 12, the dispensing means includes a parallel linkage 91. The parallel linkage 91 causes product 10 to be fed in a single row and correctly positioned over a row of open product holders 31. Product control stops 92, 93 are positioned to extend radially into and out of the feeder tube 84. Stop control bars 94 and 96 are attached to each product control stop 92, 93. In turn, the control bars 94, 96 are connected by parallel links 97, 98. As shown in FIG. 10, the parallel linkage 91 is connected to engagement bar 310 through a transfer motion means 99. In operation, as shown in FIGS. 9, 10 and 12, when engagement bar 310 moves in a direction opposite to that of product flow shown by the arrow, the motion transferred via the links 97 and 98 causes stop control bar 92 to come in contact with a tablet 10 holding that tablet in place preventing all tablets above that tablet to fall any further through the tube 84. At the same time, stop control bar 93 is withdrawn from the tube allowing a single product to fall through the tube for placement onto the carrier plate 50. Upon the motion of engagement bar 310 in the direction of product flow, motion will be transferred via links 97 and 98 to stop control bars 92 and 93 to cause control bar 93 to be reinserted into the feeder tube 84 and to release stop control bar 92 from the tubes in order to allow products 10 to drop to a position shown in FIGS. 9 and 12. It is during movement of engagement bar 310 in the direction of product flow that the tablet 10 previously released by linkage 91 is oriented and dispensed onto a product holder 30.

A more detailed view of the actual orienting and dispensing of product 10 onto the product holders is shown in FIGS. 14a and 14b. The means for depositing and orienting a tablet 10 onto an open product holder 30 in the illustrative embodiment of FIGS. 14a and 14b is a passive "knock over" mechanism. As shown, one side of the feeder tube, the side downstream of product flow, is provided with an opening 71. The remaining portion of the feeder tubes 84 extend to a position nearly touching the top of product holders 30 as shown at 72. When engagement bar 310 is moved in a direction opposite to that of product flow causing a tablet 10 to fall all the way to the bottom of feeder tube 84, the position of the product carrier 50 is such that the tablet falls onto the previously deposited tablet. The resulting position of the first released tablet is shown in FIG. 14a. Preferably, the product carrier plate 50 is positioned in relation to the feeder tubes 84 slightly off center so that the falling tablet 10 falls on a surface of the previously deposited tablet between the center of the tablet and the end of the tablet. This arrangement is preferred as compared to

allowing the tablets 10 to fall directly onto an open product holder as it has been found that severe bouncing occurs when tablets fall directly onto the holders sometimes causing disorientation or damage to the tablets. By having the tablet fall onto another tablet, the bouncing is reduced. As the engagement bar moves in the direction of product flow, the top half of tablet 10, engages the bottom edge of the opening 71 and the lower half of the tablet 10 is caused to rotate through the opening, thereby orienting the tablet with its greater diameter horizontally positioned and causing the tablet to land in that orientation onto the next open product holder as shown in FIG. 14b.

In a preferred embodiment of the present invention, the feeder means 80 is also provided with a tablet setting means 400 downstream of the feeder tubes in the direction of the product flow for properly seating the tablets in individual product holders after being dispensed from the feeder tubes. The product setting means 400 can be seen in FIGS. 9 and 10 and is shown in a detailed cross-sectional view in FIG. 15. Setting means 400 includes a setting head 402 connected to a reciprocating arm means 404 for moving the setting head from a first position out of contact with tablets 10 to a second position shown in phantom in FIG. 15 in which the head 402 contacts tablet 10. The head includes an opening 406 shaped to be complementary to the shape of the product being set. An actuating means is provided to control the reciprocating motion of the setting means. In the embodiment shown in FIG. 15, the setting means 404 is connected to engagement bar 320 which reciprocates up and down to selectively engage pins 322. In this embodiment, the setting means 400 is moved into a position to contact the tablets each time the engagement bar is caused to move into the position where pins 322 are engaged in the product holders 31. As shown in FIGS. 10 and 15, a row of setting means 400 is provided so that a row of products may be seated at a time.

In an alternative embodiment of the present invention as shown in FIG. 16, the dispensing means is comprised of a transfer means for capturing products from the feeder tubes and disposing the product in the holding fixtures or carrier plate means. In this embodiment, the dispensing means comprises a vacuum means 500 which includes a vacuum chamber 502 connected to a vacuum source for delivering a vacuum to a plurality of pick-up heads 504. An actuating means 506 is provided for positioning the vacuum pick-up heads from a first position shown at 508 for capturing products in the feeder tubes and for positioning the captured product at a second position shown at 510 for releasing the product onto the holding means. In this embodiment, the feeder tube guide means includes a seat 512 which acts as a capture seat means for retaining a single product to be transferred. A parallel linkage 514 may optionally be provided with a product control stop 516 which urges against a tablet immediately above the tablet located in the capture seat 512. The linkage 514 results in the

elimination of any force from the column of tablets on the tablet being captured that may interfere with the capture process. Alternatively, a pair of product stop bars similar to that shown in FIG. 12 may be employed. In operation, the actuating means 506 rotates the vacuum heads to the first position 508 and an extension means 516 extends the vacuum chamber 502 and the vacuum heads 504 so that the heads contact the tablets in the capture seat. The vacuum is actuated causing the tablets to be held by the vacuum heads 504. The heads 504 are then retracted removing the tablets from the seat. The retracted heads 504 with the captured tablets are then rotated to the second position where the heads 504 are again extended causing the tablets to be positioned on an empty row of product holders 31. The vacuum is released and the vacuum heads 504 retracted resulting in the tablet being deposited on the product holders.

As shown in FIG. 17, the product pick-up means 504 is comprised of an outer pick-up shell 522 having tips 524 shaped complementary to the product being captured and deposited. A vacuum tube 526 is positioned within shell 522 and may itself be extended and retracted within the shell for increasing or decreasing the vacuum force applied to the product.

As shown in FIG. 17, a product setting means 520 may also be provided with the vacuum feeder means 500. The setting means 520 is attached to the vacuum chamber 502 and is rotated throughout the various positions and is extended and retracted at the same time the vacuum pick-up heads 504 are extended and retracted. Thus, when the vacuum heads 504 are extended to deposit a tablet onto a tablet holder the setting head 520 is extended to properly seat the tablets in one or more rows downstream of the tablets being deposited.

Although certain embodiments of the methods and apparatus of the present invention have been described above with particularity, these examples are for purposes of illustration and are not limiting. Numerous variations and adaptations of the present invention as defined in the accompanying claims will immediately present themselves to those of ordinary skill.

## Claims

1. Apparatus for incrementally advancing a plurality of product carrier plate means (50) through a feeder mean (80) of a product processing system, said apparatus comprising:

first engagement means (302) or engaging one or more of said product carrier plate means (50); and characterized in that said apparatus further comprises  
first cam means (304) providing motion in at least two directions to said first engagement means (302) for moving said first engagement means (302) from a first position to a second

position to advance said product carrier plate means (50) a predetermined distance in the direction of product flow, and for returning said first engagement means (302) to said first position without moving said product carrier plate means (50), said first engagement means (302) being in engagement with said product carrier plate means (50) while in said first and second positions.

2. The apparatus of claim 1 wherein:

said first cam means (304) is a box cam providing motion in four directions for moving said first engagement means (302) to third and fourth positions in returning said first engagement means (302) to said first position, said first engagement means (302) being out of engagement with said product carrier plate means (50) in said third and fourth positions; and

said first engagement means (302) includes one or more pins (312) attached to a first engagement bar (310), said one or more pin (312) engaging one or more holes (53) disposed upon opposed side edges of said product carrier plate means (50) when said first engagement means (302) is moved into the first position.

3. The apparatus of claim 1 or claim 2 wherein:

said product carrier plate means (50) comprises one or more transverse rows of individual product holders (30, 31) and a plate adapted to retain said individual product holders;

said first cam means includes means for incrementally advancing said product carrier plate means (50) a distance equal to the center to center distance between said transverse rows of individual product holders (30, 31); said individual product holders (30, 31) comprise resilient finger means (35) for retaining said holders (30,31) in the product carrier plate means (50);

said resilient finger means (35) comprise a substantially cylindrical portion having first and second ends and two or more longitudinal slots (33) defining said resilient finger means (35); and

said individual product holders (30,31) include a shoulder portion (41) on said first end and a tapered flange (43) on said second end.

4. The apparatus of any one of claims 1 to 3, further comprising:

second engagement means (306) for engaging one or more of said product carrier plate means (50); and

second cam means (308) providing motion in two directions for moving said second engagement means (306) between a first position engaging said product carrier plate means (50) to prevent advancement thereof and a second position out of engagement with said product carrier plate means (50) to allow advancement thereof

wherein said second engagement means (306) includes one or more pins (322) attached to a second engagement bar (320), said one or more pins (322) engaging one or more holes (53) disposed upon opposed side edges of said product carrier plate means (50) when said second engagement means (306) is moved into said first position;

wherein said first cam means (304) is a box cam comprising an eccentric cam (316) rotatable 360° in a housing, each 90° of rotation providing a predetermined motion time period and a predetermined dwell time period for said first engagement means (302);

wherein said eccentric cam (316) and housing provides, for each 90° of rotation, the motion period for about 72° of rotation and the dwell time period for about 18° of rotation;

wherein said second cam means (308) is a box cam comprising an eccentric cam (326) rotatable 360° in a housing, each 180° of rotation providing a predetermined motion time period and a predetermined dwell time period for said second engagement means (306);

wherein said eccentric cam (326) and housing provide, for each 180° of rotation, the motion time period for about 72° of rotation and the dwell time period for about 108° of rotation;

wherein each of said first and second cam means (304, 306) comprises a pair of eccentric cam device (316, 326); and

wherein said pair of eccentric cam devices (326) for said second engagement means (306) includes bar means (330,331) for preventing movement of said second engagement means (306) longitudinally in the direction of product flow.

5. The apparatus of any one of claims 1 to 4 wherein:

said feeder means (80) comprises dispensing means (88) for orienting and depositing one or more products (10) onto said product carrier plate means (50), said apparatus further including means connecting said dispensing means (88) to said first cam means (304) whereby said product (10) is dispensed in con-

junction with one or more movements of said first engagement means (302);

said feeder means (80) includes one or more feeder tubes (84) which retain a plurality of products (10) in a longitudinally aligned orientation;

said product carrier plate means (50) comprises one or more transverse rows of individual product holders (30,31);

said dispensing means (88) includes parallel linkage means (91) connected to said first cam means (304) which feeds and positions a product (10) in said tubes (84) to a position proximate to each of said individual product holders (30,31) of a row of said holders;

said parallel linkage means (91) are connected to one or more product control stops (92,93) and one or more stop control bars (94,96) which cooperate to allow a single product (10) to be positioned proximate to each of said individual product holders (30,31) of a row of said holders; and

said parallel linkage means (91) is connected to said first cam means (304) such that said single product will be proximately positioned upon the return movement of said first engagement means (302).

6. The apparatus of any one of claims 1 to 5, wherein:

said feeder means (80) comprises dispensing means (88) for orienting and depositing one or more products (10) onto said product carrier plate means (50), said apparatus further including means connecting said dispensing means (88) to said first cam means (304) whereby said product is dispensed in conjunction with one or more movements of said first engagement means (302);

said feeder means (80) further comprises product setting means (400) connected to said second cam means (308) for properly seating said product (10) in individual product holders (30,31) in said product carrier plate means (50); and

said setting means (400) includes a setting head (402) connected to a reciprocating arm means (404) for moving the setting head (402) to contact and properly seat the product (10) in said individual product holders (30,31) and for moving the setting head (402) out of contact with the product (10).

7. The apparatus of any one of claims 1 to 6, wherein:

said feeder means (80) includes a hopper means (82) for containing a plurality of product (10), and further including selection mean (86),

cooperating with said hopper means (82), for eliminating partial pieces of said product (10) before said product is disposed into feeder tubes (84);

said hopper means (82) includes vibratory means (83) for agitating said product; said selection means (86) comprises a perforated plate (81) having a plurality of holes (93) with a diameter a predetermined amount smaller than the diameter of said products (10), for retaining said products and for allowing partial pieces of said products to fall through said holes (93) in response to said vibratory means; said selection means (86) further includes an elimination chute (91) for disposing of said partial pieces; and said hopper means (82) further includes delivery means (90) for transferring said properly sized products (10) retained by said perforated plate (81) to said feeder tubes (84).

8. The apparatus of any one of claims 1 to 5, wherein said feeder means comprises:

(a) hopper means for containing a plurality of products (10);  
(b) feeder tube guide means connected to said hopper means for retaining and orienting said products (10) for transfer to said carrier plate means (50);  
(c) transfer means (500) for capturing said products (10) from said feeder tube guide means and disposing said products in said carrier plate means (50), said transfer means comprising:

(i) vacuum source means (502);  
(ii) one or more vacuum pick-up heads (504) connected to said vacuum source means (502); and  
(iii) actuator means (506) for positioning said one or more vacuum pick-up heads (504) to capture and remove one or more products (10) from said feeder tube guide means and for releasing and disposing said captured products (10) into said carrier plate means (50).

9. The apparatus of claim 8 wherein:

said feeder tube guide means comprises one or more feeder tubes which retain a plurality of products (10) in a longitudinally aligned orientation, and one or more product capture seat means (512) which retain a single product (10) to be transferred;  
said feeder tube guide means further comprises parallel linkage means (514) connected

to one or more product stop bars for controlling the positioning of a single product (10) into said capture seat means (512); and

said feeder tube guide means (504) includes a pair of product stop bars for each feeder tube; further comprising product setting means for properly seating said product (10) disposed in individual product holders (30) in said carrier plate means (50).

10. A method for incrementally advancing a plurality of product carrier plate means (50) through a feeder means (80) of a product processing system, wherein said feeder means (80) comprises feeder tubes (84), said method comprising:

providing a first engagement means (302) for engaging one or more of said product carrier plate means (50) having a plurality of product holders (30) secured therein;  
moving said first engagement means (302) from a first position to a second position to advance said product carrier plate means (50) a predetermined incremental distance in a direction of product flow; and  
placing one or more products (10) onto said one or more product holders (30) when said holders (30) are in registration with said feeder tubes (84);

characterized in that said method further comprises the steps of:  
returning said first engagement means (302) to said first position without moving said product carrier plate means (50); and  
repetitively moving said first engagement means (302) from said first position to said second position and returning to said first position to repetitively cause one or more product holders (30) in said carrier plate means (50) to be in registration with one or more feeder tubes (84) of said feeder means (80).

11. A method according to claim 10, wherein said step of placing comprises the steps of:

providing a plurality of said products (10);  
retaining and orienting one or more of said products (10) in feeder tube guide means for transfer to said product carrier plate means (50);  
positioning one or more vacuum pick-up heads (504) to be in registration with said one or more products (10) in said feeder tube guide means; capturing and removing said one or more products (10) from said feeder tube guide means with said vacuum pick-up heads (504);  
position said one or more vacuum pick-up heads (504) to be in registration with one or

more product holders (30) in said product carrier plate means (50); and  
 releasing and disposing said captured products (10) into said product holders (30) from said one or more vacuum pick-up heads (504).

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## Patentansprüche

1. Vorrichtung zum schrittweisen Vorschub einer Vielzahl von Erzeugnis-Trägerplatten (50) durch eine Bestückungseinrichtung (80) eines Erzeugnis-Behandlungs-Systems, wobei diese Vorrichtung

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eine erste Eingriffseinrichtung (302) zum Eingriff in eine oder mehrere der Erzeugnis-Trägerplatten (50) aufweist und dadurch gekennzeichnet ist, daß  
 eine erste Nockeneinrichtung (304) der ersten Eingriffseinrichtung (302) eine Bewegung in mindestens zwei Richtungen erteilt, um die erste Eingriffseinrichtung (302) aus einer ersten Position in eine zweite Position zu bewegen und dadurch die Erzeugnis Trägerplatte (50) um eine vorgegebene Entfernung in Richtung des Erzeugnisflusses vorzuschieben sowie zur Rückführung der ersten Eingriffseinrichtung (302) in die erste Position, ohne dabei die Erzeugnis-Trägerplatte (50) zu bewegen, wobei die erste Eingriffseinrichtung (302) in der ersten und in der zweiten Position mit der Erzeugnis-Trägerplatte (50) im Eingriff steht.

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2. Vorrichtung nach Anspruch 1, bei welcher

die erste Nockeneinrichtung (304) ein Kastennocken ist, welcher der ersten Eingriffseinrichtung (302) eine Bewegung in vier Richtungen erteilt, um diese erste Eingriffseinrichtung (302) in die erste Position zurückzuführen, wobei die erste Eingriffseinrichtung (302) in der dritten und vierten Position außer Eingriff mit der Erzeugnis-Trägerplatte (50) bleibt und die erste Eingriffseinrichtung (302) einen oder mehrere, an einer ersten Eingriffsleiste (310) angebrachte(n) Stift(e) (312) aufweist, wobei der oder die Stift(e) (312) in ein Loch oder mehrere Löcher (53) eingreift (eingreifen), die an einander gegenüberliegenden Seitenkanten der Erzeugnis-Trägerplatte (50) angeordnet sind, wenn die erste Eingriffseinrichtung (302) in die erste Position bewegt wird.

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3. Vorrichtung nach Anspruch 1 oder 2, bei welcher

die Erzeugnis-Trägerplatte (50) eine oder mehrere Querreihe(n) einzelner Erzeugnis-Halter (30, 31) sowie eine Platte zum Halten der einzelnen Erzeugnis-Halter aufweist;

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die erste Nockeneinrichtung eine Einrichtung zum schrittweisen Vorschub der Erzeugnis-Trägerplatte (50) um eine Strecke gleich dem Mit-tenabstand zwischen den Querreihen einzelner Erzeugnis-Halter (30, 31) aufweist; die einzelnen Erzeugnis-Halter (30, 31) elastische Finger (35) zum Halten der Halter (30, 31) in der Erzeugnis-Trägerplatte (50) aufweisen; die elastischen Finger (35) aus einem im wesentlichen zylindrischen Teil mit einem ersten und einem zweiten Ende bestehen, wobei zwei oder mehr Längsschlitze (33) die elastischen Finger (35) begrenzen und die einzelnen Erzeugnis-Halter (30, 31) am jeweils ersten Ende einen Schulterbereich (41) und am jeweils zweiten Ende einen abge-schrägten Flansch (43) aufweisen.

4. Vorrichtung nach einem der Ansprüche 1 bis 3 weiterhin umfassend:

eine zweite Eingriffseinrichtung (306) zum Eingriff in eine oder mehrere Erzeugnis-Trägerplatte(n) (50) und  
 eine zweite Nockeneinrichtung (308), welche der zweiten Eingriffseinrichtung (306) eine Bewegung in zwei Richtungen erteilt, um die zweite Eingriffseinrichtung (306) zwischen einer ersten Position, wo sie mit der Erzeugnis-Trägerplatte (50) im Eingriff steht, um deren Vorschub zu verhindern, und einer zweiten Position zu bewegen, wo sie außer Eingriff mit der Erzeugnis-Trägerplatte (50) ist, um deren Vorschub zu ermöglichen;

bei welcher die zweite Eingriffseinrichtung (306) einen oder mehrere, an einer zweiten Eingriffsleiste (320) angebrachte(n) Stift(e) (322) aufweist, wobei der oder die Stift(e) (322) in ein Loch oder mehrere Löcher (53) eingreift (eingreifen), die an einander gegenüberliegenden Seitenkanten der Erzeugnis-Trägerplatte (50) angeordnet sind, wenn die zweite Eingriffseinrichtung (306) in die erste Position bewegt wird;

bei welcher die erste Nockeneinrichtung (304) ein Kastennocken mit einem in einem Gehäuse um 360° drehbaren Exzenternocken (316) ist und alle 90° der ersten Eingriffseinrichtung (302) ein vorgegebener Bewegungs-zeitraum und vorgegebener Rastzeitraum erteilt wird;

bei welcher der Exzenternocken (316) und das Gehäuse pro 90° Drehung einen Bewegungszeitraum über etwa 72° Drehung und einen Rastzeitraum über etwa 18° Drehung erzeugen;

bei welcher die zweite Nockeneinrichtung (308) ein Kastennocken mit einem in

einem Gehäuse um 360° drehbaren Exzenter-nocken (326) ist und alle 180° der zweiten Eingriffseinrichtung (306) ein vorgegebener Bewegungszeitraum und vorgegebener Rastzeitraum erteilt wird;

bei welcher der Exzenter-nocken (326) und das Gehäuse pro 180° Drehung einen Bewegungszeitraum über etwa 72° Drehung und einen Rastzeitraum über etwa 108° Drehung erzeugen;

bei welcher die erste und die zweite Nockeneinrichtung (304, 306) ein Paar Exzenter-nockenvorrichtungen (316, 326) enthält und

bei welcher das Paar der Exzenter-nockenvorrichtungen (326) für die zweite Eingriffseinrichtung (306) Leisteneinrichtungen (330, 331) aufweist, um eine Längsbewegung der zweiten Eingriffseinrichtung (306) in Richtung des Erzeugnisflusses zu verhindern.

5. Vorrichtung nach einem der Ansprüche 1 bis 4, bei welcher:

die Bestückungseinrichtung (80) eine Abgabereinrichtung (88) zum Ausrichten und Ablegen eines oder mehrerer Erzeugnisse (10) auf der Erzeugnis-Trägerplatte (50) sowie weiterhin eine Einrichtung zum Verbinden der Abgabereinrichtung (88) mit der ersten Nockeneinrichtung (304) aufweist, wodurch das Erzeugnis (10) in Verbindung mit einer oder mehreren Bewegung(en) der ersten Eingriffseinrichtung (302) abgegeben wird;

die Bestückungseinrichtung (80) ein oder mehrere Bestückungsrohr(e) (84) aufweist, welche eine Vielzahl von Erzeugnissen (10) in Längsausrichtung enthalten;

die Erzeugnis-Trägerplatte (50) eine oder mehrere Reihen einzelner Erzeugnis-Halter (30, 31) aufweist;

die Abgabereinrichtung (88) eine parallele Koppeleinrichtung (91) aufweist, welche an die erste Nockeneinrichtung (304) angeschlossen ist und ein Erzeugnis (10) in den Rohren (84) in eine Position nahe einem jeden einzelnen der Erzeugnis-Halter (30, 31) einer Reihe dieser Erzeugnis-Halter zuführt und dort positioniert; die parallelen Koppeleinrichtungen (91) mit einem Erzeugnis-Steuerungsanschlag oder mehreren Erzeugnis-Steuerungsanschlüssen (92, 93) sowie mit einer oder mehreren Anschlags-Steuerungsleiste(n) (94, 96) verbunden sind, welche derart zusammenwirken, daß es ermöglicht wird, daß ein einzelnes Erzeugnis (10) in der Nähe eines jeden einzelnen Erzeugnis-Halters (30, 31) aus einer Reihe dieser Halter positioniert wird und die parallele Koppeleinrichtung (91) mit der

ersten Nockeneinrichtung (304) derart verbunden ist, daß das einzelne Erzeugnis nach der Zurückbewegung der ersten Eingriffseinrichtung (302) in der Nähe der Erzeugnis-Halter positioniert wird.

6. Vorrichtung nach einem der Ansprüche 1 bis 5, bei welcher:

die Bestückungseinrichtung (80) eine Abgabereinrichtung (88) zum Ausrichten und Ablegen eines oder mehrerer Erzeugnisse(s) (10) auf der Erzeugnis-Trägerplatte (50) umfaßt und die Vorrichtung weiterhin eine Einrichtung aufweist, um die Abgabereinrichtung (88) mit der ersten Nockeneinrichtung (304) zu verbinden, wodurch das Erzeugnis in Verbindung mit einer oder mehreren Bewegung(en) der ersten Eingriffseinrichtung (302) abgegeben wird;

die Bestückungseinrichtung (80) weiterhin eine Erzeugnis-Ablageeinrichtung (400) umfaßt, die an die zweite Nockeneinrichtung (308) angeschlossen ist, um das einzelne Erzeugnis (10) exakt in die einzelnen Erzeugnis-Halter (30, 31) der Erzeugnis-Trägerplatte (50) einzusetzen und

die Ablageeinrichtung (400) einen an einen hin- und herbewegten Arm (404) angeschlossenen Ablagekopf (402) aufweist, um den Ablagekopf (402) zum Kontakt mit dem Erzeugnis (10) zu bewegen und das Erzeugnis (10) exakt in die einzelnen Erzeugnis-Halter (30, 31) einzusetzen sowie den Ablagekopf (402) wieder vom Erzeugnis (10) zu lösen.

7. Vorrichtung nach einem der Ansprüche 1 bis 6, bei welcher:

die Bestückungseinrichtung (80) einen Beschickungstrichter (82) zur Aufnahme einer Vielzahl der Produkte (10) und weiterhin eine mit dem Beschickungstrichter (82) zusammenwirkende Sortiereinrichtung (86) zur Abscheidung von Bruchstücken des Erzeugnisses (10), bevor dieses Erzeugnis in die Bestückungsrohre (84) gelangt, aufweist;

der Beschickungstrichter (82) einen Schwingungserzeuger (83) zum Bewegen des Erzeugnisses aufweist;

die Sortiereinrichtung (86) eine perforierte Platte (81) mit einer Vielzahl von Löchern (93) enthält, deren Durchmesser um einen vorgegebenen Betrag kleiner ist als der Durchmesser der Produkte (10), um die Produkte zurückzuhalten und Bruchstücke derselben als Reaktion auf den Schwingungserzeuger durch die Löcher (93) fallen zu lassen;

die Sortiereinrichtung (86) weiterhin eine

Abscheidungsutsche (91) zur Absonderung der Bruchstücke aufweist und der Beschickungstrichter (82) weiterhin eine Zuführeinrichtung (90) aufweist, um die von der perforierten Platte (81) zurückgehaltenen Erzeugnisse mit richtiger Größe den Bestückungsrohren (84) zuzuführen.

8. Vorrichtung nach einem der Ansprüche 1 bis 5, bei welcher die Bestückungseinrichtung umfaßt:

(a) einen Beschickungstrichter zur Aufnahme einer Vielzahl von Produkten (10);  
 (b) eine an den Beschickungstrichter angeschlossene Beschickungsrohr-Führungseinrichtung zum Halten und Ausrichten der Erzeugnisse (10) zur Überführung zur Trägerplatte (50);  
 (c) eine Überführungseinrichtung (500) zum Erfassen der Erzeugnisse (10) von der Beschickungsrohr-Führungseinrichtung und Ablage derselben auf der Trägerplatte (50), wobei die Überführungseinrichtung umfaßt:

(I) eine Vakuumquelle (502);  
 (II) einen oder mehrere an die Vakuumquelle (502) angeschlossene(n) Vakuum-Aufnehmerkopf(köpfe) (504) und  
 (III) eine Betätigungseinrichtung (506) zum Positionieren des oder der Vakuum-Aufnehmerkopfes(köpfe) (505), um ein oder mehrere Erzeugnis(se) (10) von der Bestückungsrohr-Führungseinrichtung zu erfassen sowie von dort zu entfernen und die erfaßten Erzeugnisse (10) auf der Trägerplatte (50) freizugeben und abzulegen.

9. Vorrichtung nach Anspruch 8, bei welcher:

die Bestückungsrohreinrichtung ein oder mehrere Bestückungsrohr(e), welche(s) eine Vielzahl von Erzeugnissen (10) in Längsrichtung ausgerichtet aufnimmt (aufnehmen) sowie eine oder mehrere Erzeugniserfassungs-Aufnahmeeinrichtung(en) (512), welche ein einzelnes zu überführendes Erzeugnis (10) halten, umfaßt;

die Bestückungsrohr-Führungseinrichtung weiterhin parallele Koppeleinrichtungen (514) umfaßt, die mit einer oder mehreren Erzeugnis-Stoppleiste(n) verbunden ist (sind), um die Positionierung eines einzelnen Erzeugnisses (10) in der jeweiligen Erzeugniserfassungs-Aufnahmeeinrichtung (512) zu steuern und welche weiterhin eine Erzeugnis-Ablageeinrichtung umfaßt, um das in einzelnen Erzeugnis-Haltern (30) auf der Trägerplatte befindliche Erzeugnis (10) exakt abzulegen.

10. Verfahren zum schrittweisen Vorschub einer Vielzahl von Erzeugnis-Trägerplatten (50) durch eine Bestückungseinrichtung (80) eines Erzeugnis-Behandlungs-Systems, wobei die Bestückungseinrichtung (80) Bestückungsrohre (84) aufweist und das Verfahren umfaßt:

Bereitstellen einer ersten Eingriffseinrichtung (302) zum Eingriff in eine oder mehrere Erzeugnis-Trägerplatte(n) (50) mit einer Vielzahl dort befestigter Erzeugnis-Halter (30);  
 Bewegen der ersten Eingriffseinrichtung (302) von einer ersten Position zu einer zweiten Position, um die Erzeugnis-Trägerplatten (50) um eine vorgegebene Schrittlänge in Richtung des Erzeugnisflusses vorzuschieben und  
 Plazieren eines oder mehrerer Erzeugnis(se) (10) auf dem (den) Erzeugnis-Halter(n) (30), wenn sich diese Erzeugnis-Halter (30) in genauer Ausrichtung zu den Bestückungsrohren (84) befinden;

dadurch gekennzeichnet, daß das Verfahren folgende weitere Schritte umfaßt:

Rückführen der ersten Eingriffseinrichtung (302) zur ersten Position, ohne daß die Erzeugnis-Trägerplatte (50) bewegt wird und  
 wiederholtes Bewegen der ersten Eingriffseinrichtung (302) von der ersten Position zur zweiten Position sowie wiederholtes Rückführen zur ersten Position, um einen oder mehrere Erzeugnis-Halter (30) auf der Trägerplatte (50) wiederholt zu einem oder mehreren Bestückungsrohr(en) (84) der Bestückungseinrichtung (80) auszurichten.

11. Verfahren nach Anspruch 10, bei welchem der Schritt des Plazierens folgende Schritte umfaßt:

Bereitstellen einer Vielzahl von Erzeugnissen (10);

Halten und Ausrichten eines oder mehrerer Erzeugnisse(s) (10) in der Bestückungsrohr-Führungseinrichtung, um dieselben auf die Trägerplatte (50) zu überführen;

Positionieren eines Vakuum-Aufnehmerkopfes oder mehrerer Vakuum-Aufnehmerköpfe (504) in einer zu einem oder mehreren Erzeugnis(sen) (10) in der Bestückungsrohr-Führungseinrichtung ausgerichteten Position;

Erfassen und Entnehmen eines oder mehrerer Erzeugnis(se) (10) mittels der Vakuum-Aufnehmerköpfe (504) aus der Bestückungsrohr-Führungseinrichtung;

Positionieren des einen Vakuum-Aufnehmerkopfes oder der mehreren Vakuum-Aufnehmerköpfe (504) ausgerichtet zu einem oder mehreren Erzeugnis-Halter(n) (30) auf der Erzeugnis-Trägerplatte (50) und



Freigeben und Ablegen der erfaßten Erzeugnisse (10) aus dem einen Vakuum-Aufnehmerkopf oder den mehreren Vakuum-Aufnehmerköpfen (504) in den Erzeugnis-Haltern (30).

## Revendications

1. Appareil pour l'avancement incrémentiel d'une pluralité de moyens formant plaque support de produit (50), par l'intermédiaire de moyens alimentateurs (80) d'un système de traitement de produit, ledit appareil comprenant :

des premiers moyens de mise en prise (302) destinés à mettre en prise un ou plusieurs desdits moyens formant plaque support de produit (50) ; et caractérisé en ce que ledit appareil comprend en outre :

des premiers moyens de came (304) fournissant un déplacement dans au moins deux directions auxdits premiers moyens de mise en prise (302), pour déplacer lesdits premiers moyens de mise en prise (302) d'une première position à une deuxième position, afin de faire avancer lesdits moyens formant plaque support de produit (50), sur une distance prédéterminée dans la direction du flux de produit, et pour faire revenir lesdits premiers moyens de mise en prise (302) à leur première position, sans déplacer lesdits moyens formant plaque support de produit (50), lesdits premiers moyens de mise en prise (302) étant mis en prise avec lesdits moyens formant plaque support de produit (50), tandis qu'ils se trouvent dans lesdites première et deuxième positions.

2. L'appareil selon la revendication 1, dans lequel :

lesdits premiers moyens de came (304) sont constitués d'une came en boîtier fournissant un déplacement dans quatre directions afin de déplacer lesdits premiers moyens de mise en prise (302) aux troisième et quatrième positions, lors du retour desdits premiers moyens de mise en prise (302) à ladite première position, lesdits premiers moyens de mise en prise (302) étant hors de prise desdits moyens formant plaque support de produit (50), lorsqu'on se trouve dans lesdites troisième et quatrième positions ; et

lesdits premiers moyens de mise en prise (302) comprennent une ou plusieurs broches (312), fixée(s) à une première barre de mise en prise (310), ladite une ou plusieurs broches venant en prise avec un ou plusieurs trous (53), ménagés sur des bords latéraux opposés desdits moyens formant plaque support de produit

(50), lorsque lesdits premiers moyens de mise en prise (302) sont déplacés dans la première position.

3. L'appareil selon la revendication 1 ou la revendication 2, dans lequel :

lesdits moyens formant plaque support de produit (50) comprennent une ou plusieurs rangées transversales de supports de produit individuels (30, 31) et une plaque adaptée pour retenir lesdits supports de produit individuels ; lesdits premiers moyens de came comprennent des moyens pour faire avancer de façon incrémentielle lesdits moyens formant plaque support de produit (50), d'une distance égale à la distance entre les centres desdites rangées transversales de supports de produit individuels (30, 31) ;

lesdits supports de produit individuels (30, 31) comprennent des moyens formant doigt élastique (35) destinés à retenir lesdits supports (30, 31) dans les moyens formant plaque support de produit (50) ;

lesdits moyens formant doigt élastique (35) comprennent une partie sensiblement cylindrique ayant des première et deuxième extrémités et deux ou plusieurs fentes longitudinales (33), définissant lesdits moyens formant doigt élastique (35) ; et

lesdits supports de produit individuels (30, 31) comprennent une partie épaulement (41) sur ladite première extrémité et un rebord effilé (43) prévu sur ladite deuxième extrémité.

4. L'appareil selon l'une quelconque des revendications 1 à 3, comprenant en outre :

des deuxième moyens de mise en prise (306) destinés à venir en prise avec un ou plusieurs desdits moyens formant plaque support de produit (50) ; et

des deuxième moyens de came (308) fournissant un déplacement dans deux directions pour déplacer lesdits deuxième moyens de mise en prise (306), entre une première position avec mise en prise desdits moyens formant plaque support de produit (50), en vue d'empêcher leur avancement, et une deuxième position hors de prise vis à vis desdits moyens formant plaque support de produit (50), en vue de permettre leur avancement,

dans lequel lesdits deuxième moyens de mise en prise (306) comprennent une ou plusieurs broches (322) fixée(s) à une deuxième barre de mise en prise (320), ladite une ou plusieurs broches (322) venant en prise avec un ou plusieurs trous (53) ménagés sur

des bords latéraux opposés desdits moyens formant plaque support de produit (50), lorsque lesdits deuxièmes moyens de mise en prise (306) sont déplacés à ladite première position ;

dans lequel lesdits premiers moyens de came (304) sont constitués d'une came en boîtier comprenant une came excentrique (316) susceptible de tourner sur 360° dans un boîtier, chaque rotation de 90° produisant une période de temps de déplacement prédéterminée et une période de temps d'immobilisation prédéterminée pour lesdits premiers moyens de mise en prise (302) ;

dans lequel ladite came excentrique (316) et le boîtier produisent, pour chaque rotation de 90°, la période de déplacement sur une rotation d'environ 72° et la période de temps d'immobilisation sur une rotation d'environ 18° ;

dans lequel lesdits deuxièmes moyens de came (308) sont constitués d'une came en boîtier comprenant une came excentrique (326) susceptible de tourner sur 360° dans un boîtier, chaque rotation de 180° produisant une période de temps de déplacement prédéterminée et une période de temps d'immobilisation prédéterminée, pour lesdits deuxièmes moyens de mise en prise (306) ;

dans lequel ladite came excentrique (326) et le boîtier produisent, pour chaque rotation de 180°, la période de temps de déplacement sur une rotation d'environ 72° et la période de temps d'immobilisation sur une rotation d'environ 108° ;

dans lequel chacun desdits premiers et deuxièmes moyens de came (304, 306) comprend une paire de dispositifs à came excentrique (316, 326) ; et

dans lequel ladite paire de dispositifs de came excentrique (326) destinés auxdits deuxièmes moyens de mise en prise (306) comprennent des moyens de barre (330, 331) pour empêcher le déplacement desdits deuxièmes moyens de mise en prise (306), longitudinalement dans la direction du flux de produit.

5. L'appareil selon l'une quelconque des revendications 1 à 4, dans lequel :

lesdits moyens alimentateurs (80) comprennent des moyens de distribution (88) destinés à orienter et déposer un ou plusieurs produits (10) sur lesdits moyens formant plaque support de produit (50), ledit appareil comprenant en outre des moyens reliant lesdits moyens de distribution (88) auxdits premiers moyens de came (304), de manière que ledit produit (10) soit distribué en liaison avec un ou plusieurs déplacements desdits premiers moyens de

mise en prise (302) ;

lesdits moyens alimentateurs (80) comprennent un ou plusieurs tubes alimentateurs (84) retenant une pluralité de produits (10) dans une orientation d'alignement longitudinal ;

lesdits moyens formant plaque support de produit (50) comprennent une ou plusieurs rangées transversales de supports de produit individuels (30, 31) ;

lesdits moyens de distribution (88) comprennent des moyens de liaison parallèle (91) reliés auxdits premiers moyens de came (304) alimentant et positionnant un produit (10) dans lesdits tubes (84), en une position proche de chacun desdits supports de produit individuels (30, 31) d'une rangée desdits supports ;

lesdits moyens de liaison parallèle (91) sont reliés à une ou plusieurs butées de commande de produit (92, 93) et à une ou plusieurs barres de commande de butée (94, 96), coopérant pour permettre à un produit (10) individuel d'être positionné près de chacun desdits supports de produit individuels (30, 31) d'une rangée desdits supports ; et

lesdits moyens de liaison parallèle (91) sont reliés auxdits premiers moyens de came (304), de manière que ledit produit individuel soit positionné à proximité lors du déplacement de retour desdits premiers moyens de mise en prise (302).

6. L'appareil selon l'une quelconque des revendications 1 à 5, dans lequel lesdits moyens alimentateurs (80) comprennent des moyens de distribution (88) pour orienter et déposer un ou plusieurs produits (10), sur lesdits moyens formant plaque support de produit (50), ledit appareil comprenant en outre des moyens reliant lesdits moyens de distribution (88) auxdits premiers moyens de came (304), de manière que ledit produit soit distribué en liaison avec un ou plusieurs déplacements desdits premiers moyens de mise en prise (302) ;

lesdits moyens alimentateurs (80) comprenant en outre des moyens de placement de produit (400) reliés auxdits deuxièmes moyens de came (308), afin de placer correctement ledit produit (10) dans lesdits supports de produit individuels (30, 31), dans lesdits moyens formant plaque support de produit (50) ; et lesdits moyens de placement (400) comprennent une tête de placement (402) reliée à des moyens formant bras à mouvement alternatif (404), afin de déplacer la tête de placement (402) pour l'amener en contact et placer correctement le produit (10) dans lesdits supports de produit individuels (30, 31), et pour déplacer la tête de placement (402) hors de contact

avec le produit (10).

7. L'appareil selon l'une quelconque des revendications 1 à 6, dans lequel :

lesdits moyens alimentateurs (80) comprennent des moyens formant trémie (82) destinés à contenir une pluralité de produits (10), et comprennent en outre des moyens de sélection (86) coopérant avec lesdits moyens formant trémie (82), afin d'éliminer des éléments partiels dudit produit (10), avant que ledit produit soit disposé dans lesdits tubes alimentateurs (84) ;

lesdits moyens formant trémie (82) comprennent des moyens vibratoires (83) destinés à agiter ledit produit ;

lesdits moyens de sélection (86) comprennent une plaque perforée (81) ayant une pluralité de trous (93) d'un diamètre inférieur, d'une quantité prédéterminée, au diamètre desdits produits (10), dans le but de retenir lesdits produits et de permettre à des éléments partiels desdits produits de tomber en passant à travers lesdits trous (93), en réponse à l'effet desdits moyens vibratoires ;

lesdits moyens de sélection (86) comprennent en outre une goulotte d'élimination (91) destinée à évacuer lesdits éléments partiels ; et

lesdits moyens formant trémie (82) comprennent en outre des moyens de fourniture (90) destinés à transférer lesdits produits (10), dont la taille est correcte et qui sont retenus par ladite plaque perforée (81), auxdits tubes alimentateurs (84).

8. L'appareil selon l'une quelconque des revendications 1 à 5, dans lequel lesdits moyens alimentateurs comprennent :

(a) des moyens formant trémie destinés à contenir une pluralité de produits (10) ;

(b) des moyens de guidage de tube alimentateur reliés auxdits moyens formant trémie, dans le but de retenir et d'orienter lesdits produits (10), pour les transférer auxdits moyens formant plaque support (50) ;

(c) des moyens de transfert (500) destinés à capturer lesdits produits (10) depuis lesdits moyens de guidage de tube alimentateur et disposer lesdits produits dans lesdits moyens formant plaque support (50), lesdits moyens de transfert comprenant :

(i) des moyens formant source de vide (502) ;

(ii) une ou plusieurs têtes de prélèvement sous vide (504), reliées auxdits moyens

formant source de vide (502) ; et

(iii) des moyens actionneurs (506) destinés à positionner ladite une ou plusieurs têtes de prélèvement sous vide (504), pour capturer et enlever une ou plusieurs produits (10) desdits moyens de guidage de tube alimentateur, et pour relâcher et disposer lesdits produits capturés (10) dans lesdits moyens formant plaque support (50).

9. L'appareil selon la revendication 8, dans lequel :

lesdits moyens de guidage de tube alimentateur comprennent un ou plusieurs tubes alimentateurs retenant une pluralité de produits (10), en une orientation alignée longitudinalement, et un ou plusieurs moyens formant siège de capture de produit (512), qui retiennent un produit (10) individuel devant être transféré ;

lesdits moyens de guidage de tube alimentateur comprenant en outre des moyens de liaison parallèle (514) reliés à une ou plusieurs barres de butée de produit, pour commander le positionnement d'un produit individuel (10) dans lesdits moyens formant siège de capture (512) ; et

lesdits moyens de guidage de tube alimentateur (504) comprennent une paire de barres de butée de produit pour chaque tube alimentateur ;

comprenant en outre des moyens de placement de produit pour placer correctement ledit produit (10) disposé dans des supports de produit individuels (30), dans lesdits moyens formant plaque support (50).

10. Un procédé pour l'avancement incrémentiel d'une pluralité de moyens formant plaque support de produit (50), par l'intermédiaire de moyens alimentateurs (80) d'un système de traitement de produit, dans lequel lesdits moyens alimentateur (80) comprennent des tubes alimentateurs (84), ledit procédé comprenant :

la fourniture de premiers moyens de mise en prise (302) destinés à mettre en prise un ou plusieurs desdits moyens formant plaque support de produit (50), ayant une pluralité de supports de produit (30) y étant fixés ;

le déplacement desdits premiers moyens de mise en prise (302), d'une première position à une deuxième position, pour faire avancer lesdits moyens formant plaque support de produit (50) sur une distance incrémentielle prédéterminée dans une direction de flux de produit ; et le placement d'un ou plusieurs produits (10) sur lesdits un ou plusieurs supports de produit (30), lorsque lesdits supports (30) sont en coïn-

cidence avec lesdits tubes alimentateurs (84) ;  
 caractérisé en ce que ledit procédé  
 comprend en outre les étapes consistant à :  
 ramener lesdits premiers moyens de mise en  
 prise (302) à ladite première position, sans 5  
 déplacer lesdits moyens formant plaque sup-  
 port de produit (50) ; et  
 déplacer répétitivement lesdits premiers  
 moyens de mise en prise (302) de leur dite pre- 10  
 mière position à ladite deuxième position, et les  
 ramener à ladite première position pour provo-  
 quer répétitivement la mise en coïncidence  
 d'un ou plusieurs supports de produit (30) se 15  
 trouvant dans lesdits moyens formant plaque  
 support (50), vis à vis d'un ou plusieurs tubes  
 alimentateurs (84) desdits moyens alimenta-  
 teurs (80).

11. Un procédé selon la revendication 10, dans lequel  
 ladite étape de placement comprend les étapes 20  
 consistant à :

fournir une pluralité desdits produits (10) ;  
 retenir et orienter un ou plusieurs desdits pro-  
 duits (10) dans les moyens de guidage de tube 25  
 alimentateur en vue d'effectuer le transfert  
 auxdits moyens formant plaque support de pro-  
 duit (50) ;  
 positionner une ou plusieurs têtes de prélève-  
 ment sous vide (504), de manière à les faire 30  
 coïncider avec lesdits un ou plusieurs produits  
 (10) se trouvant dans lesdits moyens de gui-  
 dage de tube alimentateur ;  
 capturer et enlever lesdits un ou plusieurs pro-  
 duits (10) desdits moyens de guidage de tube 35  
 alimentateur avec lesdites têtes de prélève-  
 ment sous vide (504) ;  
 positionner lesdites une ou plusieurs têtes de  
 prélèvement sous vide (504) pour les faire 40  
 coïncider vis à vis des un ou plusieurs supports  
 de produit (30), dans lesdits moyens formant  
 plaque support de produit (50) ; et  
 relâcher et placer lesdits produits (10) capturés  
 dans lesdits supports de produit (30) depuis 45  
 lesdites une ou plusieurs têtes de prélèvement  
 sous vide (504).

50

55

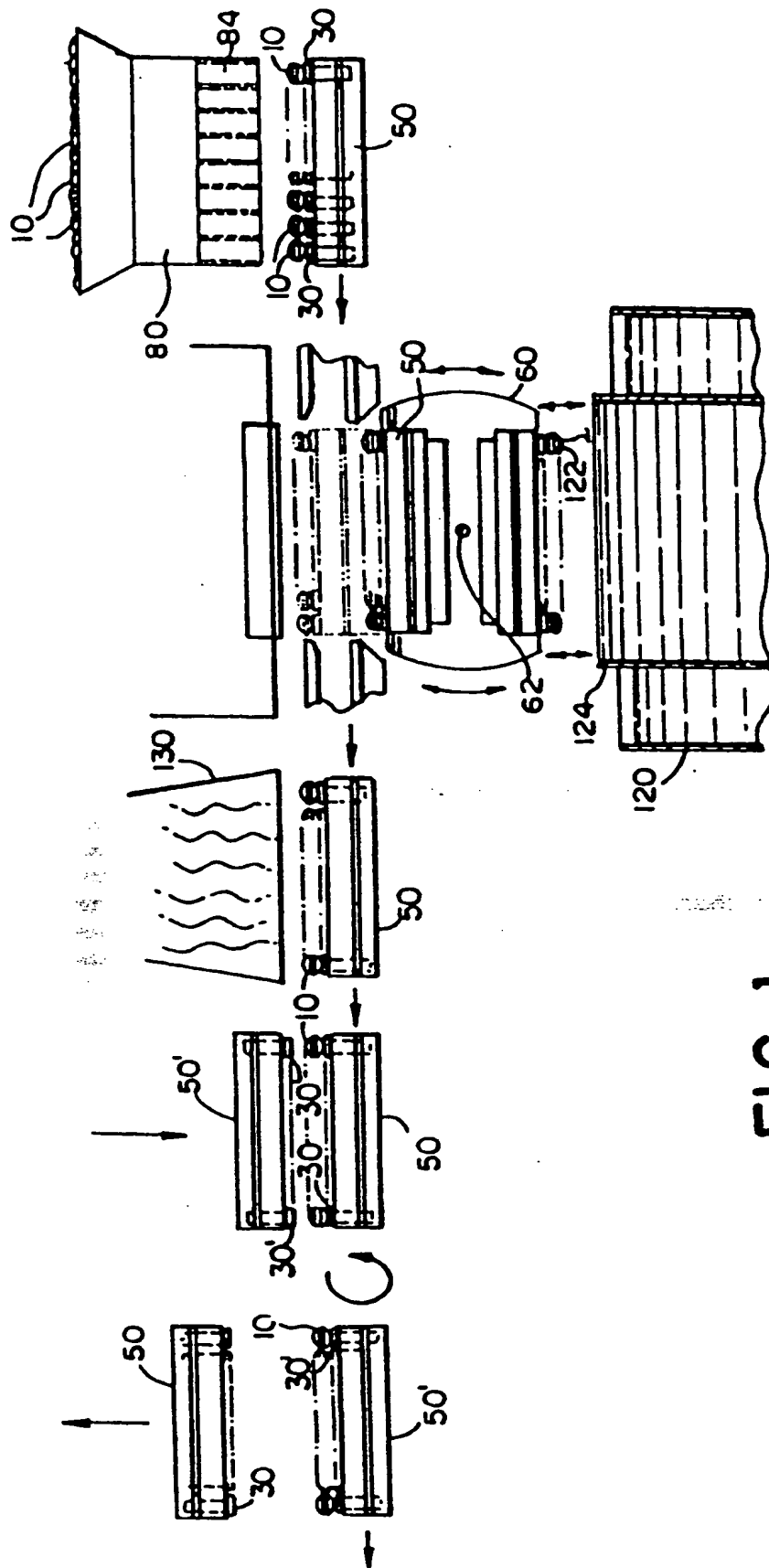


FIG. 1

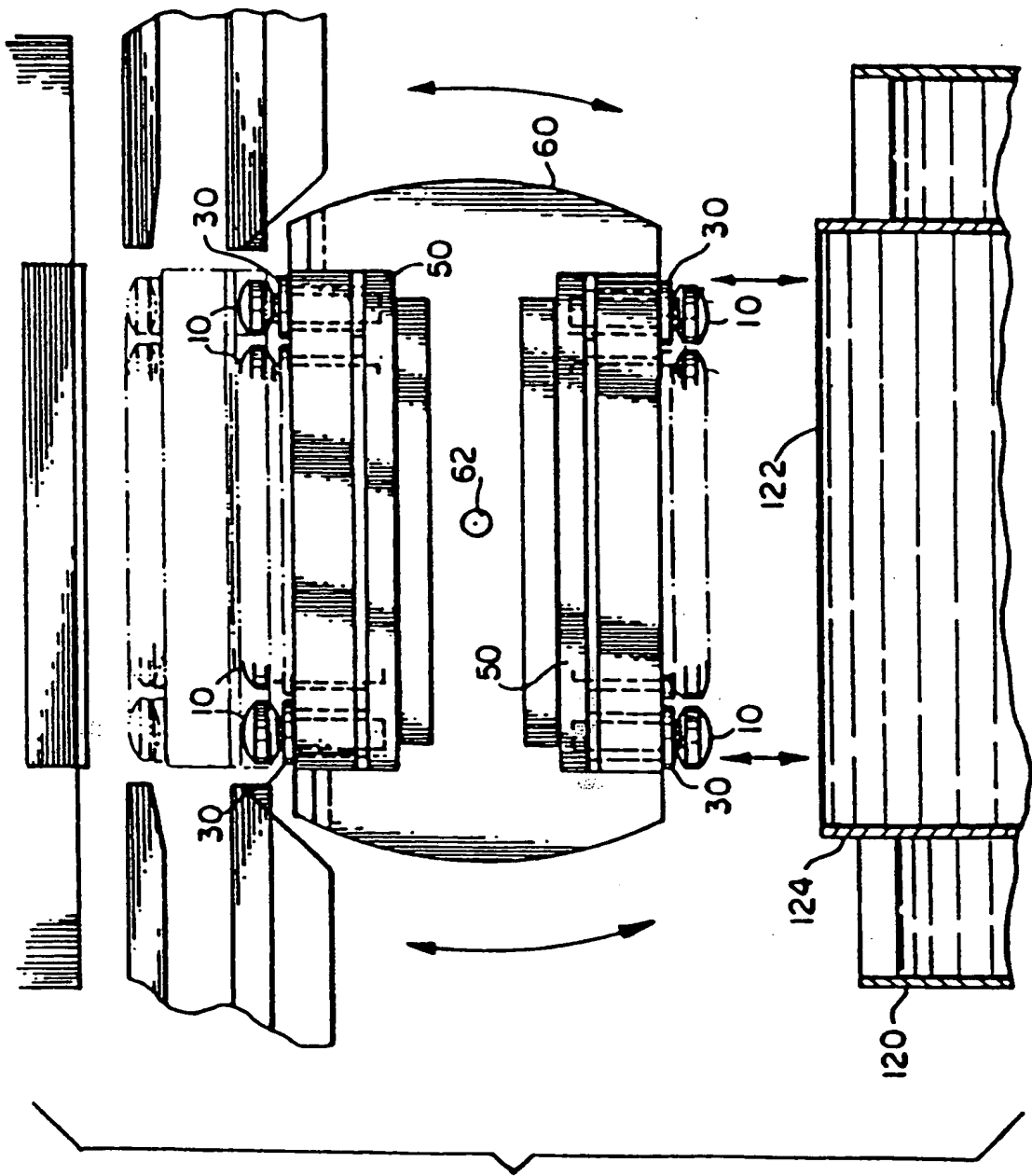
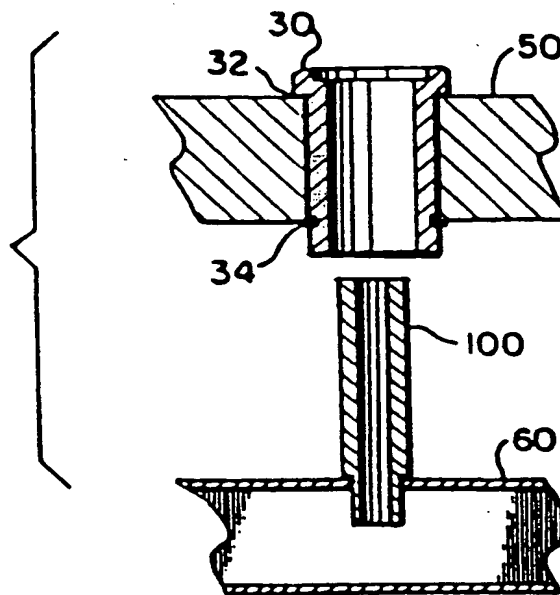
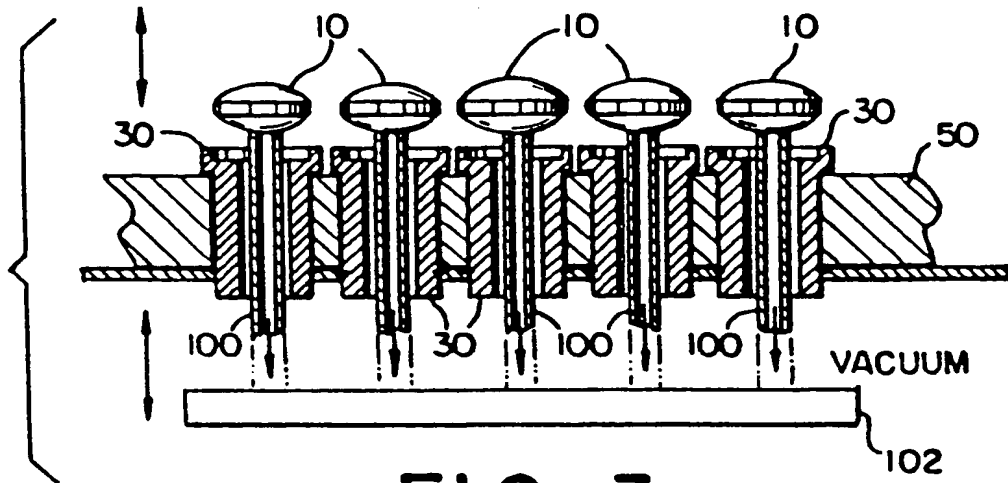


FIG. 2



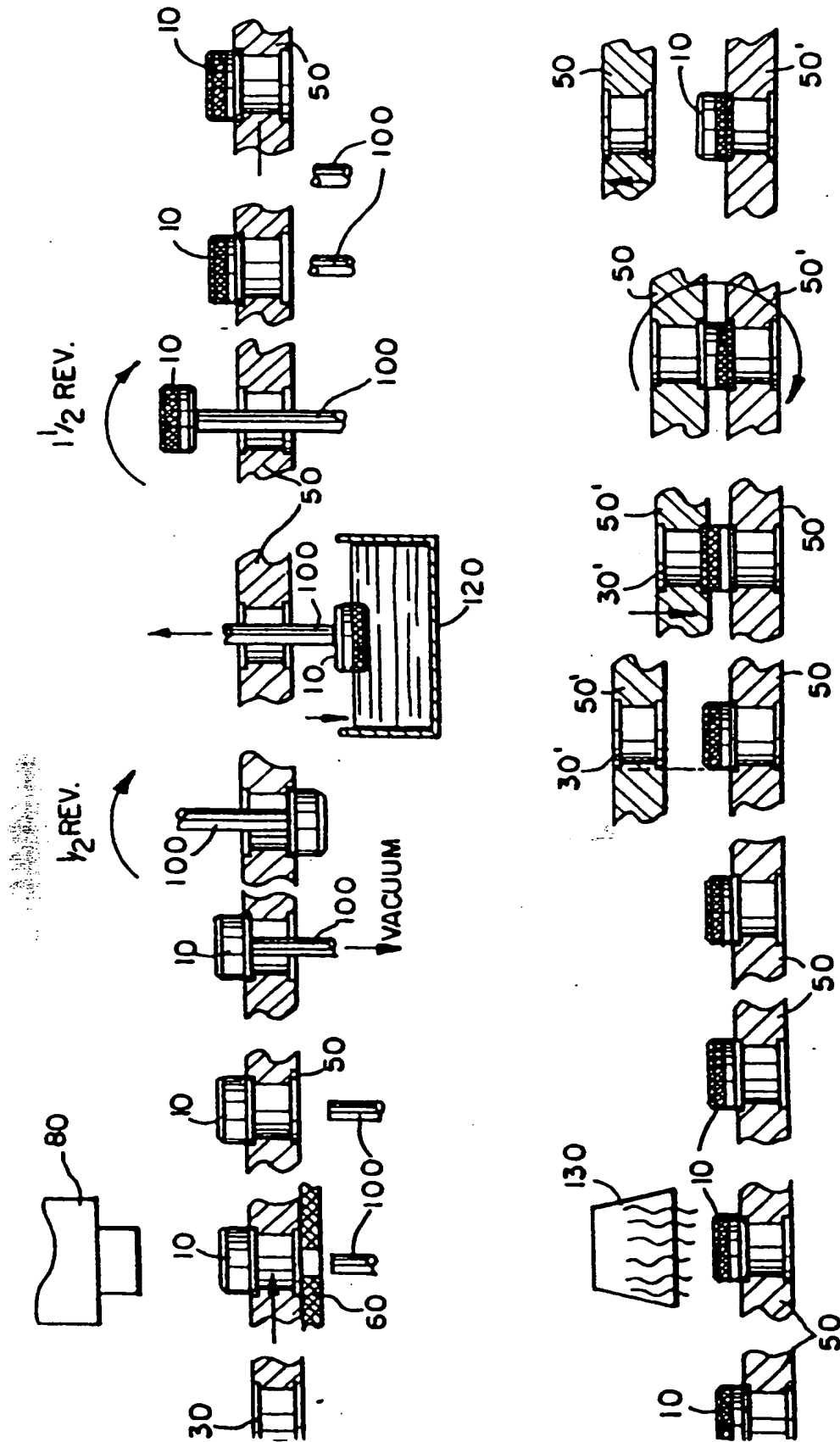
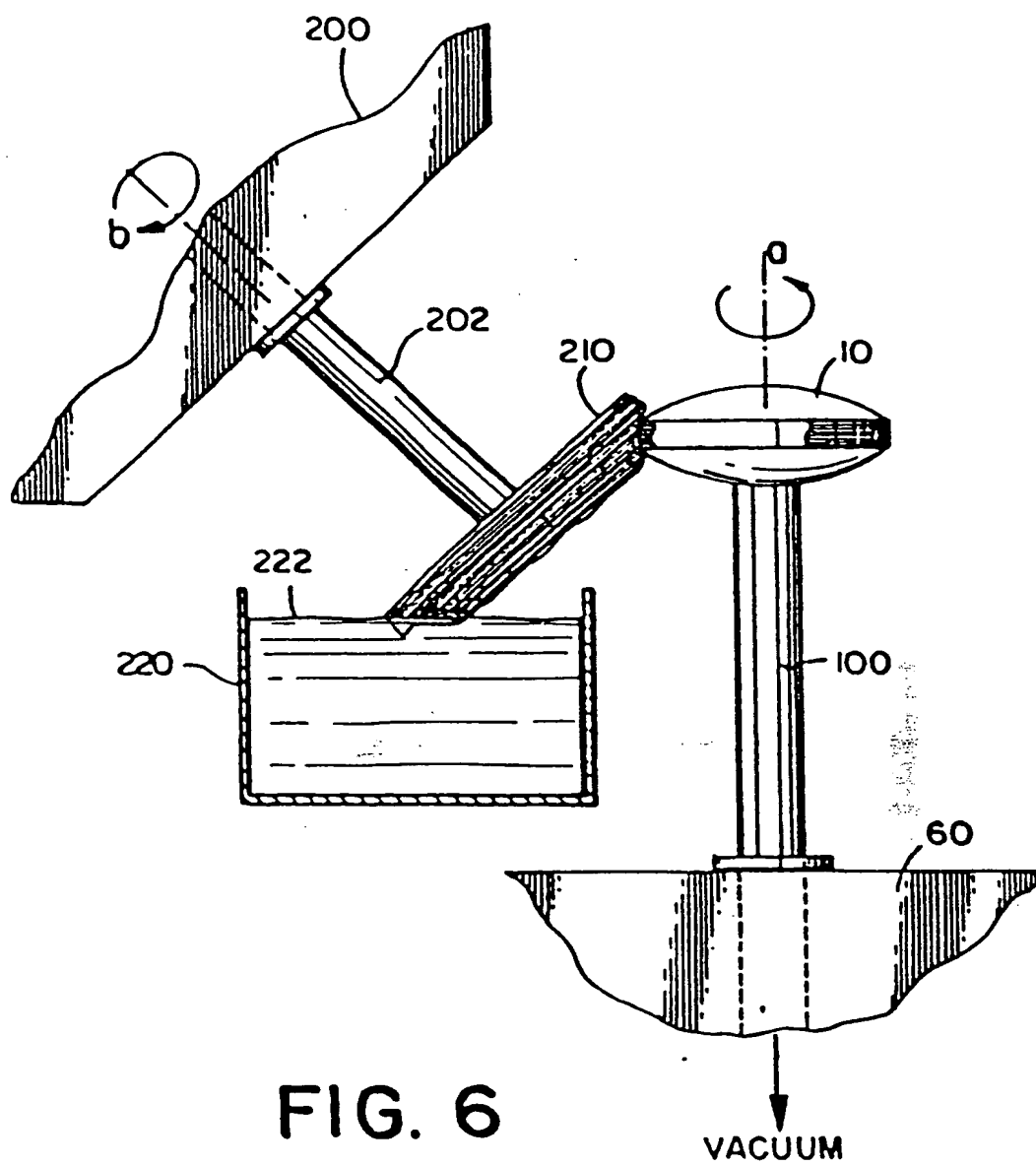


FIG. 5





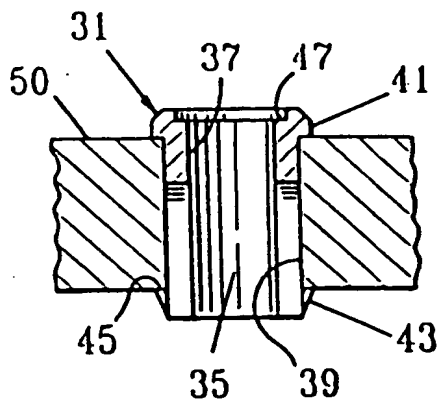


FIG. 7A

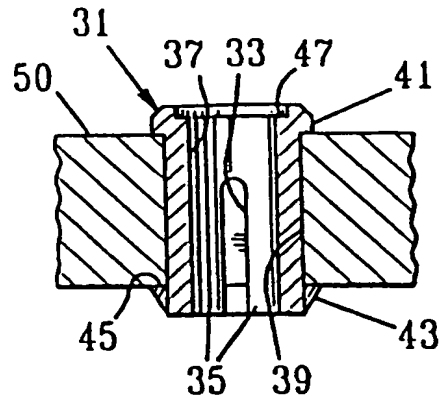


FIG. 7B

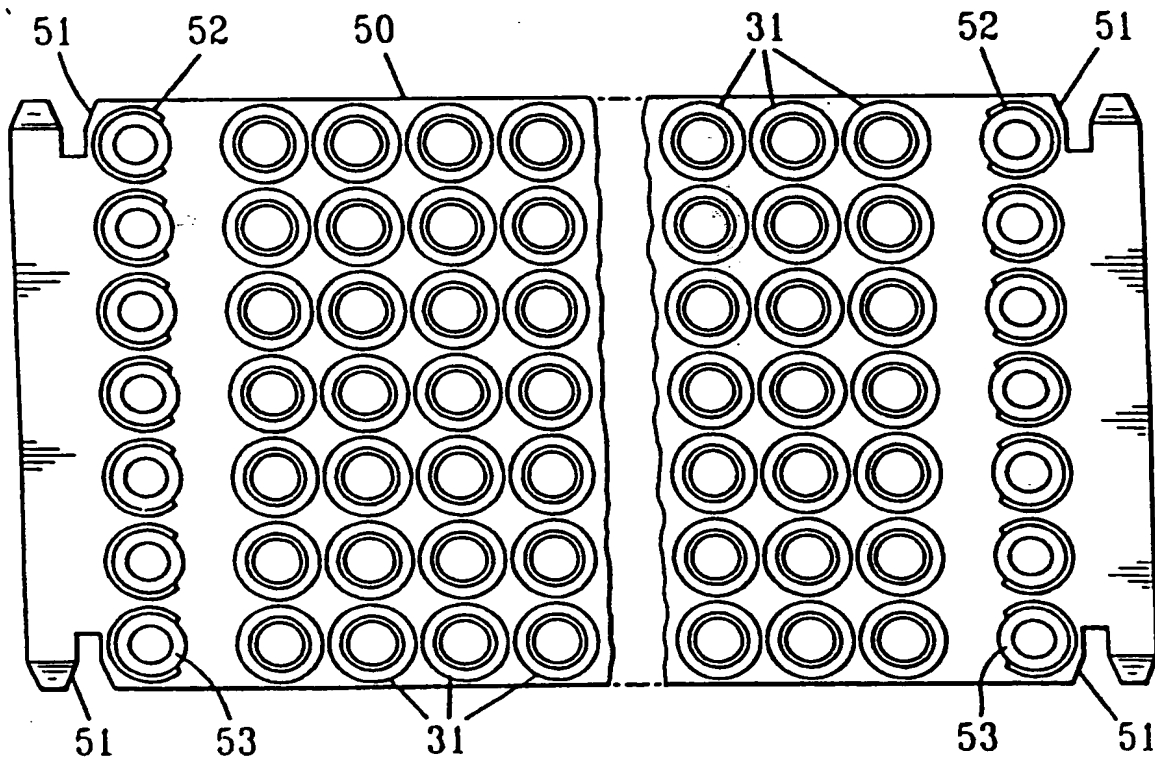


FIG. 8

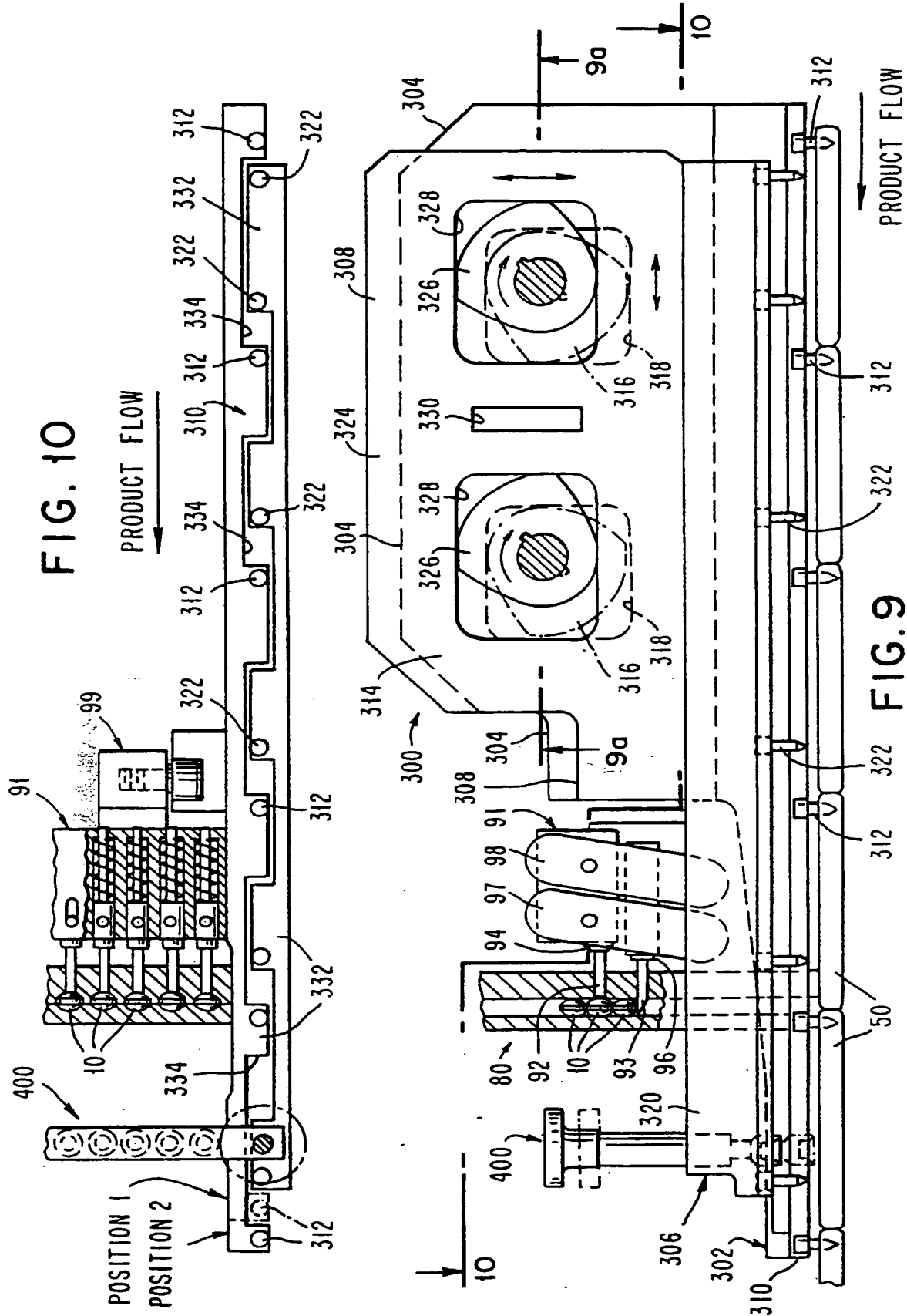
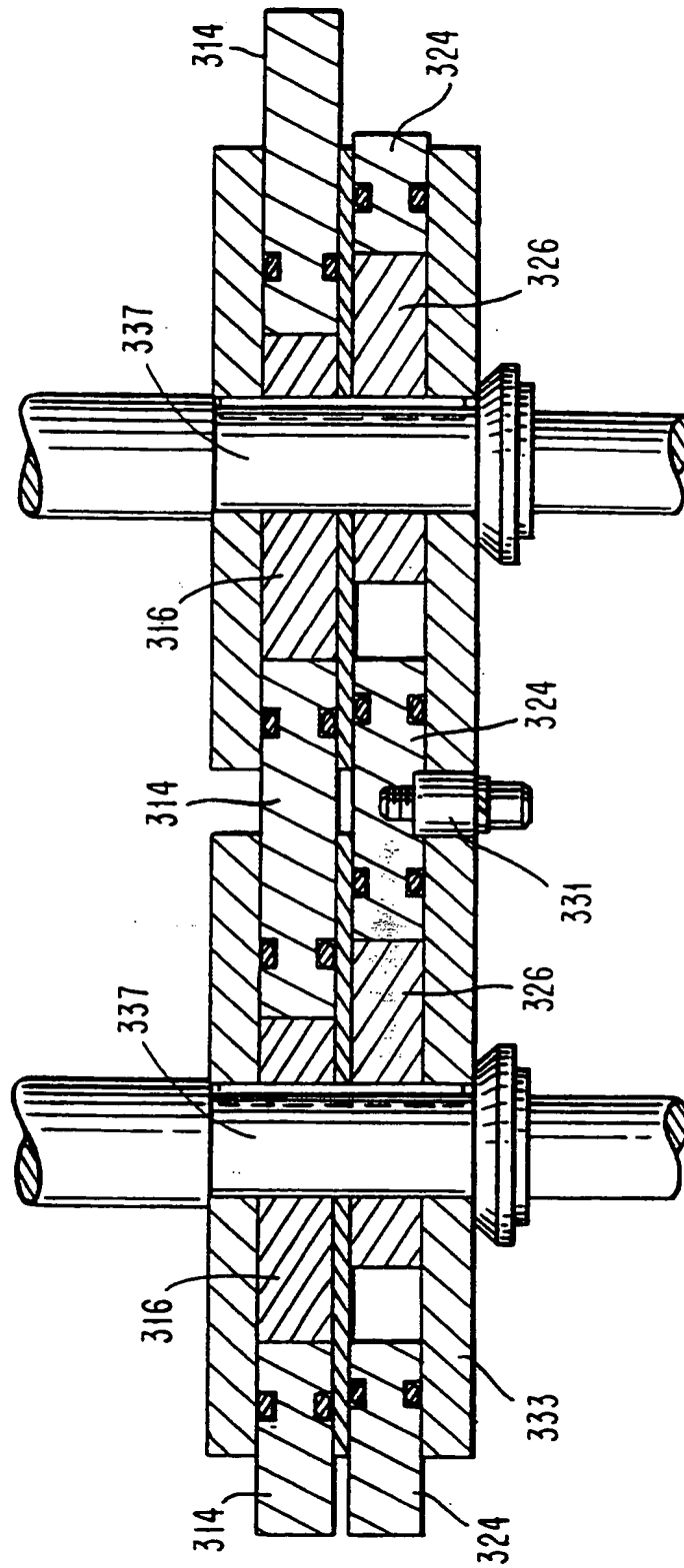
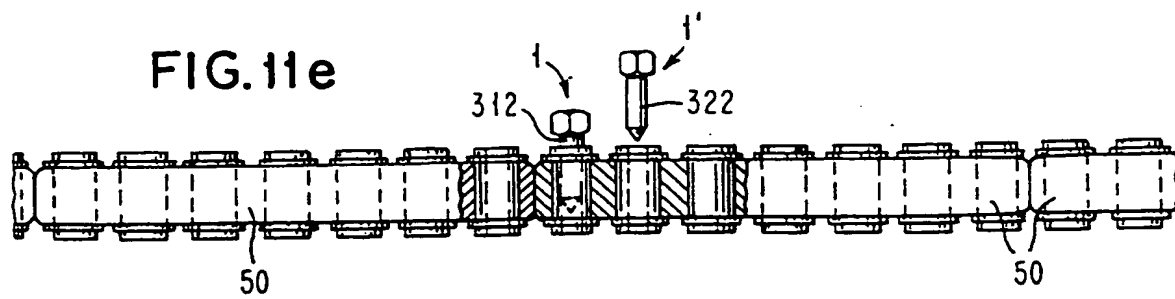
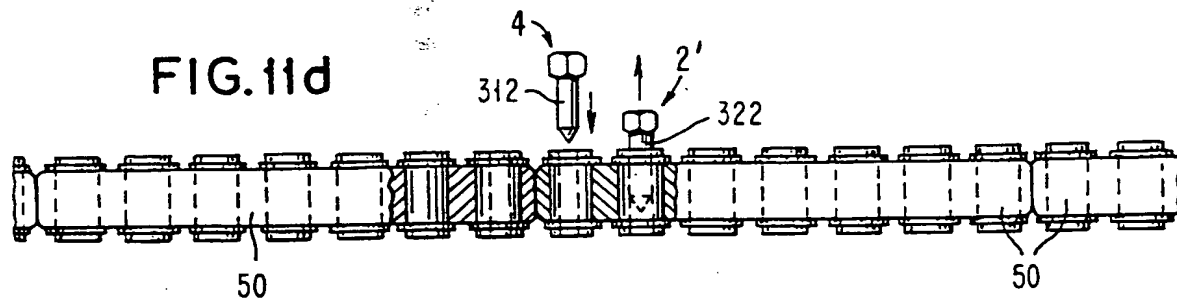
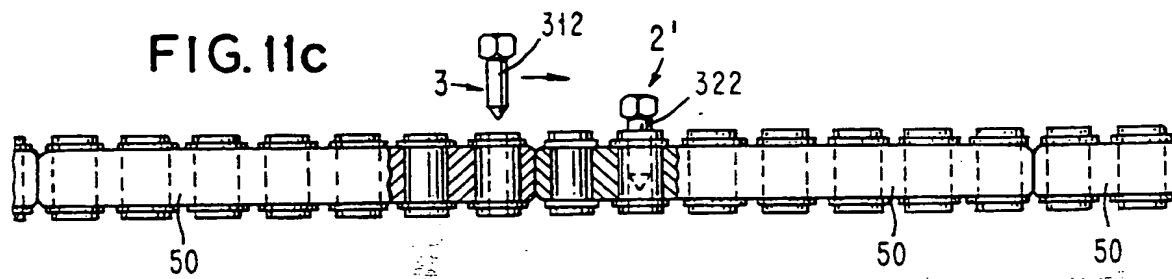
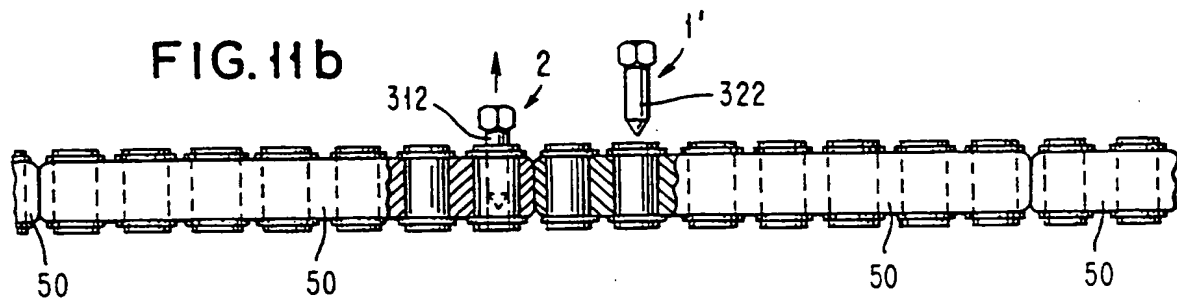
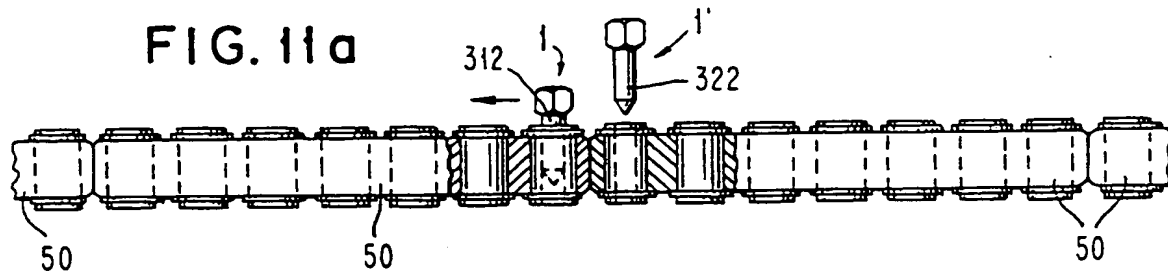
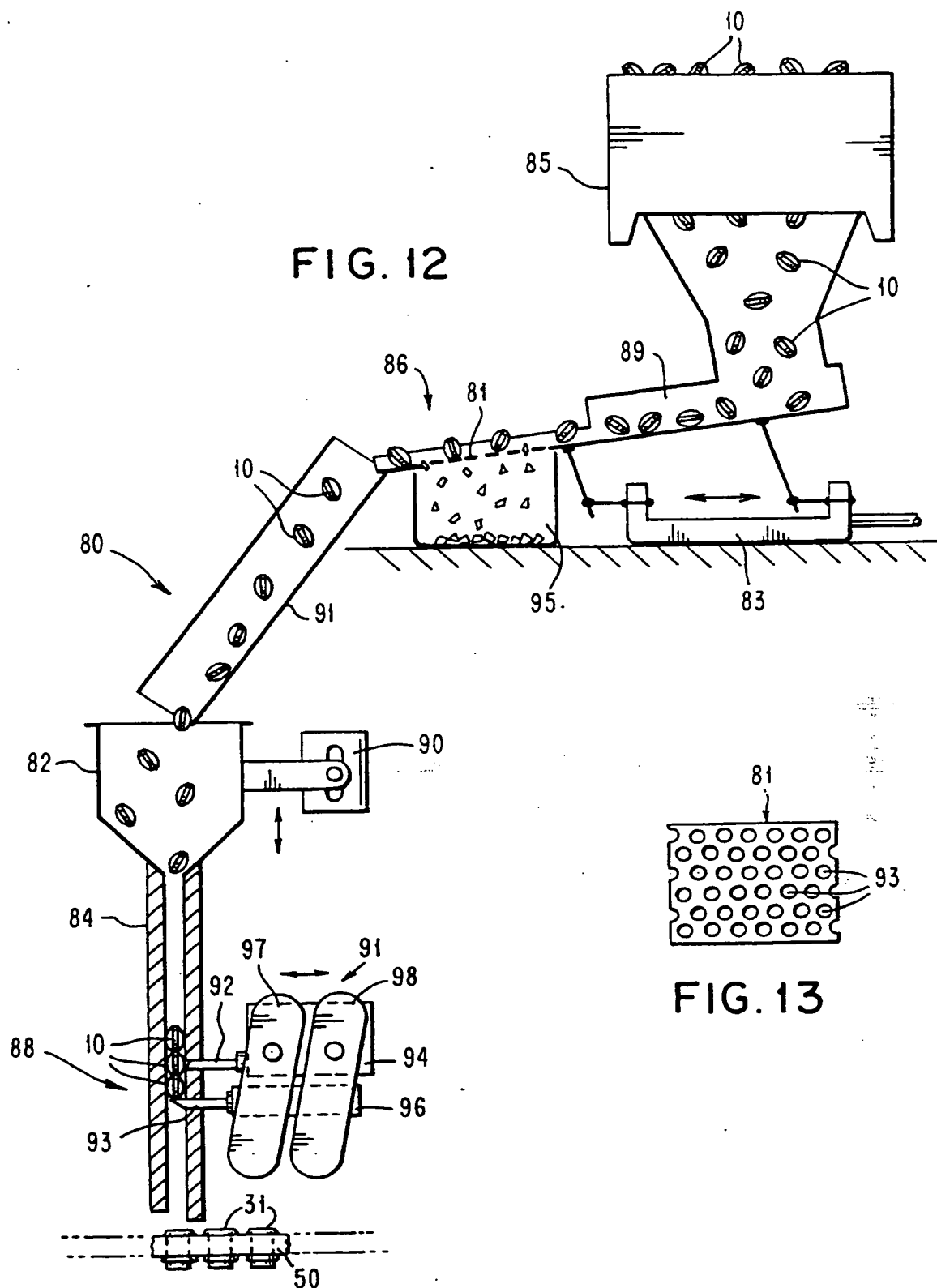


FIG. 9a







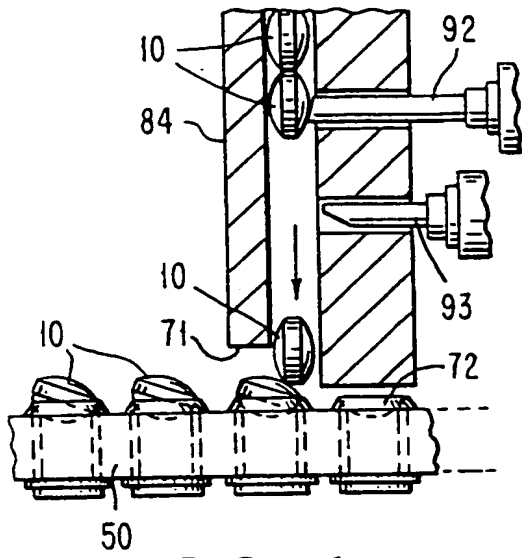


FIG. 14a

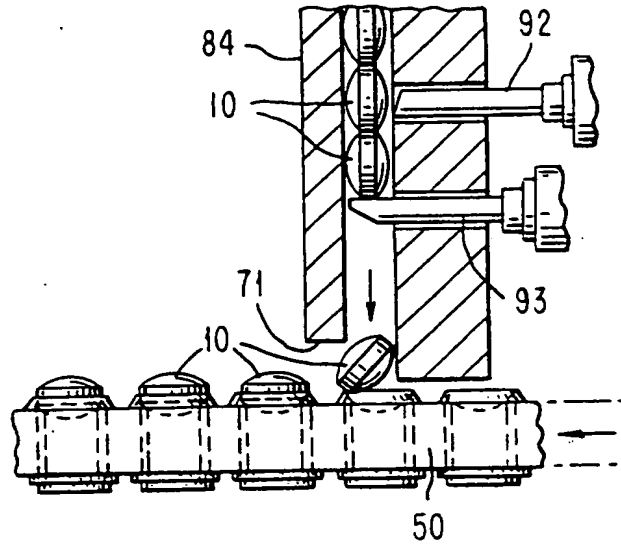


FIG. 14b

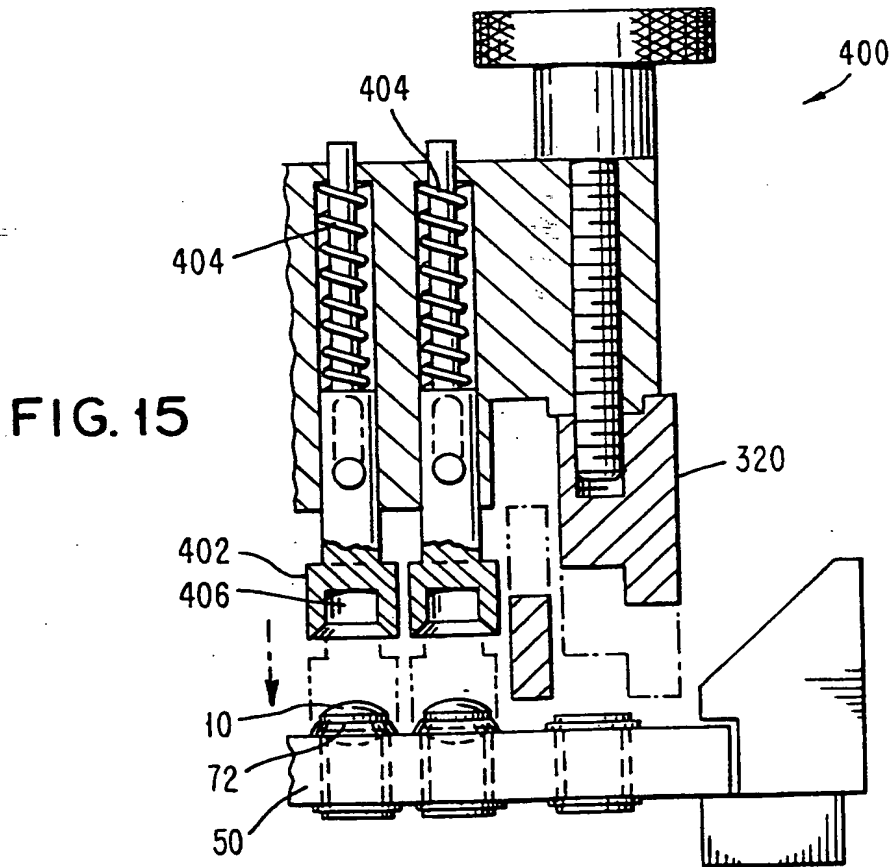


FIG. 15

FIG. 16

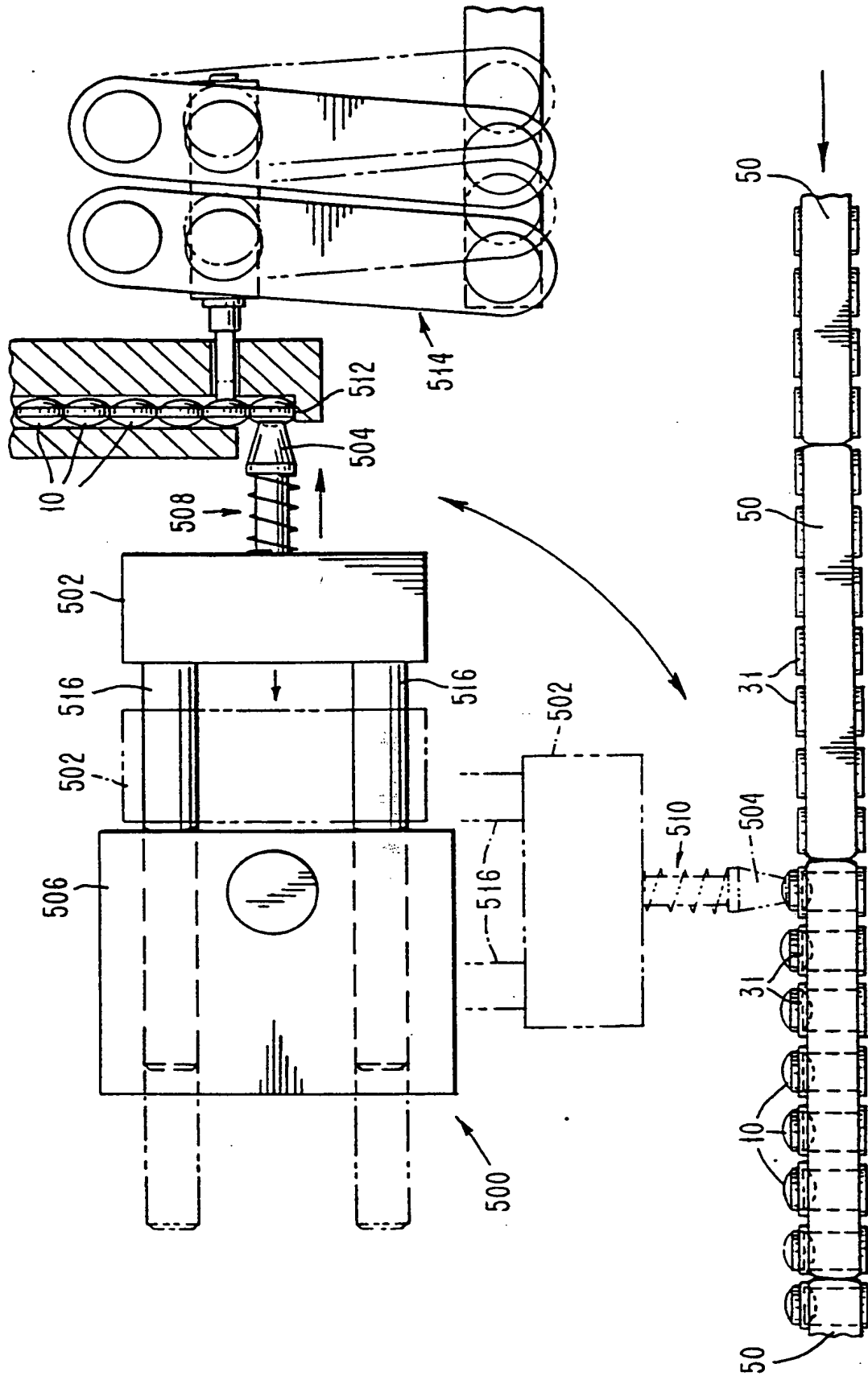




FIG. 17

